

# Axial Piston Variable Pump A4VG

**RE 92003/06.12** Replaces: 06.09

1/68

#### **Data sheet**

Series 32 Size 28 to 250 Nominal pressure 400 bar Maximum pressure 450 bar Closed circuit



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### **Features**

- Variable axial piston pump of swashplate design for hydrostatic drives in closed circuit.
- The flow is proportional to the drive speed and displacement.
- The flow can be infinitely varied by adjusting the swashplate angle.
- Flow direction changes smoothly when the swashplate is moved through the neutral position.
- A wide range of highly adaptable control devices with different control and regulating functions, for all important applications.
- Two pressure-relief valves are provided on the high-pressure side to protect the hydrostatic transmission (pump and motor) from overload.
- The high-pressure relief valves also function as boost valves.
- The integrated boost pump acts as a feed pump and control pressure supply.
- The maximum boost pressure is limited by a built-in lowpressure relief valve.
- As standard with integrated pressure cut-off

# Ordering code for standard program

A	4V G			D					/	32		_	Ν									
0	1 02	03	04	05	06	07	08	09		10	11		12	13	14	15	16	17	18	19 2	20 2	1 22
	Axial pis	ston u	ınit																			
	Swashp			ı, varia	able, ı	nomin	al pre	essure	400	) bar,	maxin	num p	ress	ure 4	150 b	ar						A4V
	Operatir	a m	ndo.																			
	Pump, c			uit																		G
	Sizes (N					- ا حا - ا	-4	l		0					140	- FC	74		1405	100	050	i
03	Geomet	ric ai	spiace	emen	, see	table	or va	lues	on pa	ge 8				28	40	56	71	90	125	180	250	
	Control	devic	es											28	40	56	71	90	125	180	250	
	Without	cont	rol mo	odule									_	•	•	•	•	•	•	•	•	NV
	Proportional control pilot-pressure related p = 6 to 18 bar mechanical servo <sup>1)</sup>														•	•	•	•	•	•	•	HD3
															•	•	•	•	•	•	•	HW
	Proportional control  electric  U = 12 V DC													•	•	•	•	•	•	•	•	EP3
04				1 4 - 2								24 V	-	•	•	•	•	•	•		•	EP4 EZ1
	Iwo-poi	we-point control electric														•	•	•			•	EZ1
	Automa	U = 24  V D Automatic control speed-related $U = 12  V D$																				DA1
	ratoma	utomatic control speed-related $U = 12 \text{ V }$ $U = 24 \text{ V }$																				DA1
	Hydraul	ic cor	ntrol. d	direct	contr	olled								•	•							DG
	Pressur					5)								28	40	56	71	90	125	180	250	
05	Pressur	e cut-	off (S	tanda	ra)									•	•	•		•	•	•	•	D
	Neutral	posit	ion s	witch	(only	for H	W, se	e pa	ge 13	3)				28	40	56	71	90	125	180	250	
06	Without				switc	h (wit	thout	code	)					•	•	•	•	•	•	•	•	
	Neutral	positi	on sw	vitch										•	•	•	•	•	•	•	•	L
	Mechan	ical s	troke	limit	er (se	e pag	ge 56	)						28	40	56	71	90	125	180	250	
07	Without	mecl	hanica	al stro	ke lim	niter (	witho	ut co	de)					•	•	•	•	•	•	•	•	
07	Mechan	ical s	troke	limite	r, exte	rnally	adju	stable	)					•	•	•	•	•	•	•	•	М
	Ports X <sub>3</sub>	. X 4 f	or str	okino	ı chai	mber	pres	sure	(see	page	56)			28	40	56	71	90	125	180	250	
	Without								(	<u> </u>	,			•	•	•	•	•	•	•	•	
80	Ports X <sub>3</sub>							ıre						•	•	•	•	•	•	•	•	Т
	DA cont	rol va	ilve (s	see pa	age 17	7)					,		, , , , , , , , , , , , , , , , , , ,		NV	HD	HW	DG	DA	EP	EZ	
	Without DA control valve												•	•	•	•	-	•	•	1		
	DA con	DA control valve fixed setting												_	•	•	•	•	•	_	2	
	DA control valve mechanically actuating direction right											-	•	•	•	•	•	_	3R			
09												_	•	•	•	•	•	_	3L			
	DA control valve fixed setting and braking inch valve mounted, control with brake fluid according to ISO 4 no mineral oil									492	5,	-	_	-	_	•	_	_	4			
									b	ased	on mi	neral	oil		_	_	-	_	•	_	_	8
	DA cont	rol val	ve fixe	ed set	ting, p	orts f	or pilo	ot con	trol d	evice					-	•	•	•	•	•	-	7

<sup>1)</sup> On delivery, the position of the lever may differ from that shown in the brochure or drawing. If necessary, the position of the lever can be adjusted by the customer.

# Ordering code for standard program

A4V	G			D					/	32		ı	Z										
01	02	03	04	05	06	07	08	09		10	11		12	13	14	15	16	17	18	19	20	21	22

#### **Series**

1	0   Series 3, index 2	32

#### **Directions of rotation**

١,	Viewed on drive shaft	clockwise	R
'		counter-clockwise	L

#### Seals

.	12	NBR (nitrile-caoutchouc), shaft seal in FKM (fluor-caoutchouc)	N	1
	1	11211 (mino cacatoricae), chartecan military (maci cacatoricae)		- 1

	Drive shafts (permis	sible input torques see page 9)	28	40	56	71	90	125	180	250	
	Splined shaft	for single pump	•	•	•	•	•	•	•	•	Z
	DIN 5480	for combination pump - 1st pump	_2)	•	•	•	•	•	_2)	_2)	Α
13	Splined shaft	for single pump	•	•	•	•	•	•	•	•	S
	ANSI B92.1a	for combination pump - 1st pump	_3)	_3)	•	•	_3)	•	•	•	T
		Only for combination pump – 2nd pump	_	•	-	_	•	_	-	ı	U

	Mounting flanges		28	40	56	71	90	125	180	250	
	SAE J744	2-hole	•	•	•	-	-	-	-	-	С
14		4-hole	-	-	-	_	-	_	•	•	D
		2+4-hole	-	_	-	•	•	•	-	-	F

 Service line ports
 28
 40 to 180
 250

	SAE flange ports A and B,		suction port S	bottom	_	•	-	02
1	top and bottom			top	_	0	-	03
'	SAE flange ports A and B,	right	suction port S	bottom	•	-	•	10
	same side	left		top	0	_	0	13

	Boost pump		28	40	56	71	90	125	180	250	
	Without integrated boost pump without throu	ıgh drive	•	•	•	•	•	•	•	•	N00
16	with through	drive	•	•	•	•	•	•	•	•	K
16	Integrated boost pump without throu	ıgh drive	•	•	•	•	•	•	•	•	F00
	with through	drive	•	•	•	•	•	•	•	•	F

Through drives (mounting options, see page 53)

	Flange SAE J744 <sup>4)</sup>	Coupling for splined shaft	28	40	56	71	90	125	180	250	
	82-2 (A)	5/8 in 9T 16/32DP <sup>5)</sup>	•	•	•	•	•	•	•	•	.01
	101-2 (B)	7/8 in 13T 16/32DP <sup>5)</sup>	•	•	•	•	•	•	•	•	.02
		1 in 15T 16/32DP <sup>5)</sup>	•	•	•	•	•	•	•	•	.04
17	127-2 (C)	1 in 15T 16/32DP <sup>5)</sup>	-	•	_	_	_	-	-	_	.09
		1 1/4 in 14T 12/24DP <sup>5)</sup>	-	-	•	•	•	•	•	•	.07
	152-2/4 (D)	W35 2x16x9g <sup>6)</sup>	-	_	-	_	•	_	-	_	.73
		1 3/4 in 13T 8/16DP <sup>5)</sup>	-	_	-	_	_	•	•	•	.69
	165-4 (E)	1 3/4 in 13T 8/16DP <sup>5)</sup>	-	_	_	_	_	_	•	•	.72

 $\bullet$  = Available  $\bigcirc$  = On request - =

-= Not available

= Preferred program

- 2) Standard for combination pump 1st pump: shaft Z
- 3) Standard for combination pump 1st pump: shaft S
- 4) 2 = 2-hole; 4 = 4-hole
- 5) Coupling for splined shaft according to ANSI B92.1a
- 6) Coupling for splined shaft according to DIN 5480

= Preferred program

# Ordering code for standard program

A	4V	/ G			D					/	32		_	N									
С	1	02	03	04	05	06	07	08	09		10	11		12	13	14	15	16	17	18	19 2	20 2	1 22
	Va	lves (s	see p	age 5	4)			;	Settin	g ran	ge ∆p	)			28	40	56	71	90	125	180	250	
	Hi	igh-pre	ssure	e relief	valve	, pilot	opera	ated	100 tc	420	) bar	with	bypa	ss	-	-	-	•	•	•	•	•	1
		igh-pre						:	250 to	420	) bar	w/o	bypas	ss	•	•	•	-	-	-	-	_	3
18	dir	rect co	ntroll	led, fix	ed se	tting						with	bypa	ss	•	•	•	_	-	-	_	_	5
								-	100 to	250	) bar	w/o	bypas	ss	•	•	•	-	-	-	_	_	4
												with	bypa	ss	•	•	•	-	-	-	_	_	6
	Filtration boost circuit / external supply (see pages 57 to 60)														28	40	56	71	90	125	180	250	
	Filtration in the boost pump suction line														•	•	•	•	•	•	•	•	S
	Filtration in the boost pump pressure line																	,					
	F	Ports f	or ex	ternal	boos	t circ	uit filt	ration	(F <sub>e</sub> a	nd Fa	<u>,</u> )					•	•	•			•	_	D
	and cold start valve - • • • • -														_	K							
19	Filter mounted with cold start valve														-	•	•	•	•	•	•	_	F
		Filter n	art v	alve a	nd	ins	pection	on wii	ndow						-	•	•	•	•	•	•	_	Р
	contamination indica-					ele	ctric	signal							-	•	•	•	•	•	•	_	В
	Ex	ternal s	supply	y (on v	ersion	witho	ut inte	grate	d boos	t pun	np – N	00, K	)		•	•	•	•	•	•	•	•	Е
	Sw	vivel a	ngle	sens	or (se	e pag	ge 61)	)							28	40	56	71	90	125	180	250	
		/ithout							de)						•	•	•	•	•	•	•	•	
20	El	ectric	swive	el ang	le ser	nsor m	nount	ed <sup>7)</sup>							•	•	•	•	•	•	•	•	R
	Со	nnect	or fo	r sole	enoid	<b>s</b> 8) (se	ee pa	ge 62	2)						28	40	56	71	90	125	180	250	
21	DI	EUTS	CH n	nolded	b	witl	hout s	suppr	essor	diod	е				•	•	•	•	•	•	•	•	Р
21	connector, 2-pin with suppressor diode								de (c	nly fo	r EZ a	and D	A)	•	•	•	•	•	•	•	•	a	
	Sta	andar	d/s	pecia	lvers	ion																	
	St	tandar	d ver	sion					W	thou	t code	9											
									cc	mbir	ned w	ith at	tachm	ent p	oart o	r atta	chmer	nt pum	ıp				-K
22	Special version																				-S		
									cc	mbir	ned w	ith att	tachm	ent p	oart o	r atta	chmer	t pur	np				-SK

<sup>7)</sup> Please contact us if the swivel angle sensor is used for control

- = Not available

O = On request

■ = Available

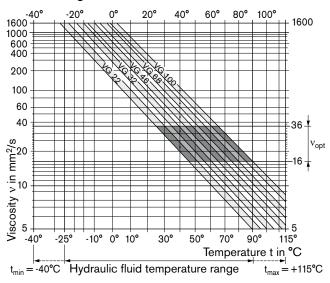
<sup>8)</sup> Connectors for other electric components can deviate

### Hydraulic fluid

Before starting project planning, please refer to our data sheets RE 90220 (mineral oil), RE 90221 (environmentally acceptable hydraulic fluids) and RE 90222 (HFD hydraulic fluids) for detailed information regarding the choice of hydraulic fluid and application conditions.

The variable pump A4VG is not suitable for operation with HFA, HFB and HFC hydraulic fluids. If HFD or environmentally acceptable hydraulic fluids are used, the limitations regarding technical data or other seals must be observed. Please contact us.

#### Selection diagram



### Details regarding the choice of hydraulic fluid

The correct choice of hydraulic fluid requires knowledge of the operating temperature in relation to the ambient temperature: in a closed circuit, the circuit temperature.

The hydraulic fluid should be chosen so that the operating viscosity in the operating temperature range is within the optimum range ( $v_{opt}$  see shaded area of the selection diagram). We recommended that the higher viscosity class be selected in each case.

Example: At an ambient temperature of X  $^{\circ}$ C, an operating temperature of 60  $^{\circ}$ C is set in the circuit. In the optimum operating viscosity range ( $v_{opt}$ , shaded area), this corresponds to the viscosity classes VG 46 and VG 68; to be selected: VG 68.

#### Note

The case drain temperature, which is affected by pressure and speed, can be higher than the circuit temperature. At no point of the component may the temperature be higher than 115 °C. The temperature difference specified below is to be taken into account when determining the viscosity in the bearing.

If the above conditions cannot be maintained due to extreme operating parameters, please contact us.

#### Viscosity and temperature of hydraulic fluid

	-		
	Viscosity [mm <sup>2</sup> /s]	Temperature	Comment
Transport and storage at ambient temperature		$T_{min} \ge -50 ^{\circ}\text{C}$ $T_{opt} = +5 ^{\circ}\text{C} \text{ to } +20 ^{\circ}\text{C}$	Factory preservation: up to 12 months with standard, up to 24 months with long-term
(Cold) start-up <sup>1)</sup> $v_{\text{max}} = 1600$		$T_{St} \ge -40  ^{\circ}C$	$t \leq 3$ min, without load (p $\leq 50$ bar), n $\leq 1000$ rpm
Permissible temperatu	re difference	$\Delta T \le 25 \text{ K}$	between axial piston unit and hydraulic fluid
Warm-up phase	v < 1600 to 400	T = -40 °C to -25 °C	at $p \leq 0.7$ • $p_{nom},  n \leq 0.5$ • $n_{nom}$ and $t \leq 15$ min
Operating phase			
Temperature difference	Э	$\Delta T = approx. 5 K$	between hydraulic fluid in the bearing and at port T
Maximum temperature		115 °C	in the bearing
		110 °C	measured at port T
Continuous operation	v = 400  to  10 $v_{opt} = 36 \text{ to } 16$	T = -25 °C to +90 °C	measured at port T, no restriction within the permissible data
Short-term operation	$v_{min} \ge 7$	T <sub>max</sub> = +110 °C	measured at port T, t < 3 min, p < 0.3 • p <sub>nom</sub>
FKM shaft seal <sup>1)</sup>		T ≤ +115 °C	see page 7

<sup>1)</sup> At temperatures below -25 °C, an NBR shaft seal is required (permissible temperature range: -40 °C to +90 °C).

#### Filtration of the hydraulic fluid

Finer filtration improves the cleanliness level of the hydraulic fluid, which increases the service life of the axial piston unit.

To ensure the functional reliability of the axial piston unit, a gravimetric analysis of the hydraulic fluid is necessary to determine the amount of solid contaminant and to determine the cleanliness level according to ISO 4406. A cleanliness level of at least 20/18/15 is to be maintained.

Depending on the system and the application, for the A4VG, we recommend

#### Filter cartridges $\beta_{20} \ge 100$ .

With an increasing differential pressure at the filter cartridges, the  $\beta$  value must not deteriorate.

At very high hydraulic fluid temperatures (90 °C to maximum 115 °C), a cleanliness level of at least 19/17/14 according to ISO 4406 is necessary.

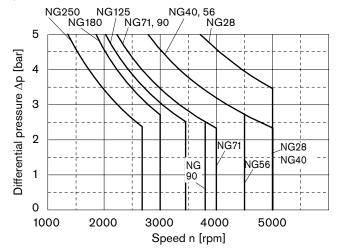
If the above classes cannot be achieved, please contact us. For notes on filtration types, see page 57.

#### Shaft seal

#### Permissible pressure loading

The service life of the shaft seal is influenced by the speed of the axial piston unit and the case drain pressure (case pressure  $p_G$ ). The mean differential pressure of 2 bar between the case and the ambient pressure may not be enduringly exceeded at normal operating temperature. For a higher differential pressure at reduced speed, see diagram. Momentary pressure spikes (t < 0.1 s) of up to 10 bar are permitted. The service life of the shaft seal decreases with an increase in the frequency of pressure spikes.

The case pressure must be equal to or higher than the ambient pressure.



These values are valid for an ambient pressure  $p_{abs} = 1$  bar.

#### Temperature range

The FKM shaft seal may be used for case drain temperatures from -25 °C to +115 °C.

#### Note

For application cases below -25 °C, an NBR shaft seal is required (permissible temperature range: -40 °C to +90 °C). State NBR shaft seal in plain text when ordering. Please contact us.

### Operating pressure range

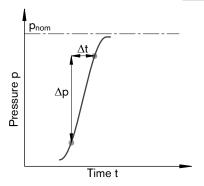
(operating with mineral oil)

#### Pressure at service line port A or B

Nominal pressure  $p_{nom}$ 400 bar absoluteMaximum pressure  $p_{max}$ 450 bar absoluteSingle operating period10 sTotal operating period at  $n_{nom}$ 300 hMinimum pressure (high-pressure side)25 bar absoluteMinimum pressure (low-pressure side)10 bar over  $p_G$ 

(boost pressure setting must be higher, depending on system)

Rate of pressure change  $R_{A \text{ max}}$  9000 bar/s



#### **Boost pump**

#### Pressure at suction port S

Maximum pressure p<sub>Sp max</sub> \_\_\_\_\_\_40 bar absolute

#### Control pressure

To ensure the function of the control, the following control pressure is required depending on the speed and operating pressure (measuring point, port P<sub>S</sub>):

For controls EP, HW and HD Minimum control pressure  $p_{St \, min}$  (at n = 2000 rpm) \_\_\_\_\_ 20 bar over  $p_{G}$  For control DA, DG, EZ Minimum control pressure  $p_{St \, min}$  (at n = 2000 rpm) \_\_\_\_\_ 25 bar over  $p_{G}$ 

#### Note

Values for other hydraulic fluids, please contact us.

 $p_G$  = case pressure

#### Definition

#### Nominal pressure pnom

The nominal pressure corresponds to the maximum design pressure.

#### Maximum pressure p<sub>max</sub>

The maximum pressure corresponds to the maximum operating pressure within the single operating period. The sum of the single operating periods must not exceed the total operating period.

#### Minimum pressure (high-pressure side)

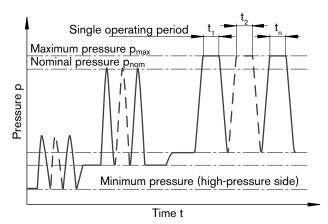
Minimum pressure at the high-pressure side (A or B) which is required in order to prevent damage to the axial piston unit.

#### Minimum pressure (low-pressure side)

Minimum pressure at the low-pressure side (A or B) which is required in order to prevent damage to the axial piston unit.

### Rate of pressure change $R_{\text{A}}$

Maximum permissible rate of pressure rise and reduction during a pressure change over the entire pressure range.



Total operating period =  $t_1 + t_2 + ... + t_n$ 

Table of values (theoretical values, without efficiency and tolerances; values rounded)

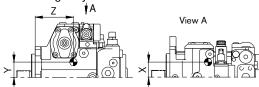
Size			NG		28	40	56	71	90	125	180	250
Displacement geometric, p	per revo	olution										
variable pump			$V_{g max}$	cm <sup>3</sup>	28	40	56	71	90	125	180	250
boost pump (at $p = 20 \text{ k}$	bar)		V <sub>g Sp</sub>	cm <sup>3</sup>	6.1	8.6	11.6	19.6	19.6	28.3	39.8	52.5
Speed <sup>1)</sup>												
maximum at $V_{g max}$	maximum at V <sub>g max</sub>			rpm	4250	4000	3600	3300	3050	2850	2500	2400
limited maximum <sup>2)</sup>			n <sub>max</sub>	rpm	4500	4200	3900	3600	3300	3250	2900	2600
intermittent maximum <sup>3)</sup>			n <sub>max</sub>	rpm	5000	5000	4500	4100	3800	3450	3000	2700
minimum			n <sub>min</sub>	rpm	500	500	500	500	500	500	500	500
Flow												
at $n_{\text{nom}}$ and $V_{\text{g max}}$			$q_{\nu}$	L/min	119	160	202	234	275	356	450	600
Power <sup>4)</sup>												
at $n_{nom}$ , $V_{g max}$ and	$\Delta p = 4$	00 bar	Р	kW	79	107	134	156	183	238	300	400
Torque <sup>4)</sup>												
at $V_{g max}$ and	$\Delta p = 4$	00 bar	T	Nm	178	255	357	452	573	796	1146	1592
_	$\Delta p = 1$	00 bar	Т	Nm	45	64	89	113	143	199	286	398
Rotary stiffness drive shaft	t	S	С	kNm/rad	31.4	69	80.8	98.8	158.1	218.3	244.5	354.5
		Т	С	kNm/rad	_	_	95	120.9	_	252.1	318.4	534.3
		Α	С	kNm/rad	_	79.6	95.8	142.4	176.8	256.5	_	_
		Z	С	kNm/rad	32.8	67.5	78.8	122.8	137	223.7	319.6	624.2
		U	С	kNm/rad	_	50.8	_	_	107.6	_	_	_
Moment of inertia for rotar	y group	)	$J_{GR}$	kgm <sup>2</sup>	0.0022	0.0038	0.0066	0.0097	0.0149	0.0232	0.0444	0.0983
Maximum angular accelera	ation <sup>5)</sup>		α	rad/s <sup>2</sup>	38000	30000	24000	21000	18000	14000	11000	6700
Case volume			V	L	0.9	1.1	1.5	1.3	1.5	2.1	3.1	6.3
Mass approx. (without through drive)		rive)	m	kg	29	31	38	50	60	80	101	156
Center of gravity <sup>6)</sup>			Х	mm	< 5	< 5	< 5	< 5	< 5	< 5	< 5	< 5
			Υ	mm	24	20	20	15	20	30	33	30
			Z	mm	105	112	106	135	145	160	180	203

- 1) The values are valid:
  - for the optimum viscosity range from  $\nu_{\text{opt}} = 36 \text{ to } 16 \text{ mm}^2\text{/s}$
  - with hydraulic fluid based on mineral oils
- 2) Limited maximum speed:
  - at half of corner power (e. g. at  $V_{g max}$  and  $p_N$  /2)
- 3) Intermittent maximum speed:
  - at high idle speed
  - at overspeed:  $\Delta p = 70$  to 150 bar and  $V_{g\;max}$
  - at reversing peaks:  $\Delta p < 300$  bar and t < 0.1 s.
- 4) Without boost pump
- 5) The data are valid for values between the minimum required and maximum permissible speed.

Valid for external excitation (e.g. engine 2 to 8 times rotary frequency; cardan shaft twice the rotary frequency). The limit value applies for a single pump only.

The load capacity of the connection parts must be considered.

6) Center of gravity



Operation above the maximum values or below the minimum values may result in a loss of function, a reduced service life or in the destruction of the axial piston unit. We recommend testing the loads by means of experiment or calculation / simulation and comparison with the permissible values.

### Permissible radial and axial forces of the drive shafts

Splined shaft DIN 5480

Size		NG		28	40	40	56	56	71	71	90
Drive shaft				W25	W30	W35	W30	W35	W35	W40	W35
Maximum radial force at	Fq	F <sub>q max</sub>	N	3030	3608	3092	5051	4329	5489	4803	6957
distance a (from shaft collar)	a	a	mm	17.5	17.5	20	17.5	20	20	22.5	20
Maximum axial	Fax + -	- F <sub>ax max</sub>	N	1557	2120	2120	2910	2910	4242	4242	4330
force	Fax I — I	+ F <sub>ax max</sub>	κN	417	880	880	1490	1490	2758	2758	2670

Size		NG		90	125	125	180	250
Drive shaft				W45	W40	W45	W50	W55
Maximum radial force at	Fq	F <sub>q max</sub>	N	5411	8455	7516	9740	12298
distance a (from shaft collar)	a	a	mm	25	22.5	25	27.5	29
Maximum axial	= +ſħ	- F <sub>ax max</sub>	N	4330	6053	6053	7500	4150
force	rax	+ F <sub>ax max</sub>	N	2670	3547	3547	4500	4150

### Splined shaft ANSI B92.1a

Size		NG		28	40	40	56	56	71	71	90
Drive shaft			in	1	1	1 1/4	1 1/4	1 3/8	1 1/4	1 3/8	1 1/4
Maximum radial force at	Fq	F <sub>q max</sub>	N	2983	4261	3409	4772	4338	6050	5500	7670
distance a (from shaft collar)	a	a	mm	19	19	24	24	24	24	24	24
Maximum axial	- +III	- F <sub>ax max</sub>	ι N	1557	2120	2120	2910	2910	4242	4242	4330
force	Fax ±==	+ F <sub>ax ma</sub>	x N	417	880	880	1490	1490	2758	2758	2670

Size		NG		90	125	125	180	180	250	250
Drive shaft			in	1 3/4	1 3/4	2	1 3/4	2 1/4	1 3/4	2 1/4
Maximum radial force at	Fq	F <sub>q max</sub>	N	5478	7609	6658	10956	8522	15217	11836
distance a (from shaft collar)	a	a	mm	33.5	33.5	40	33.5	40	33.5	40
Maximum axial	= +1h	- F <sub>ax max</sub>	N	4330	6053	6053	7500	7500	4150	4150
force	Fax ± = =	+ F <sub>ax max</sub>	ι N	2670	3547	3547	4500	4500	4150	4150

#### Note

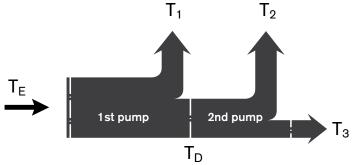
Special requirements apply in the case of belt drive and cardan shaft. Please contact us.

### Permissible input and through-drive torques

Size	NG		28	40	56	71	90	125	180	250	
Torque at $V_{g max}$ and $\Delta p = 4$	Т	Nm	178	255	357	452	573	796	1146	1592	
Input torque at drive shaft, n	naximum <sup>2)</sup>										
DIN 5480	Z	T <sub>E max</sub>	Nm	352	522	522	912	912	1460	3140	4350
				W25	W30	W30	W35	W35	W40	W50	W55
	A	T <sub>E max</sub>	Nm	-	912	912	1460	2190	2190	_	_
					W35	W35	W40	W45	W45		
ANSI B92.1a (SAE J744)	S	T <sub>E max</sub>	Nm	314	602	602	602	1640	1640	1640	1640
				1 in	1 1/4 in	1 1/4 in	1 1/4 in	1 3/4 in	1 3/4 in	1 3/4 in	1 3/4 in
	T	T <sub>E max</sub>	Nm	_	-	970	970	-	2670	4070	4070
						1 3/8 in	1 3/8 in		2 in	2 1/4 in	2 1/4 in
	U <sub>3)</sub>	T <sub>E max</sub>	Nm	-	314	_	_	602	_	_	_
				1 in			1 1/4 in				
Maximum through-drive torq	Maximum through-drive torque <sup>4)</sup>		Nm	231	314	521	660	822	1110	1760	2230

- 1) Efficiency not considered
- 2) For drive shafts without radial force
- 3) Shaft "U" is only permissible as a drive shaft for the 2nd pump in a combination pump of the same size.
- 4) Note maximum input torque at shaft S!

#### Torque distribution



 $T_E$  and  $T_D$  consists as follows:

$$T_E = T_1 + T_2 + T_3$$
 $T_D = T_2 + T_3$ 
 $T_E < T_{E max}$ 
 $T_D < T_{D max}$ 

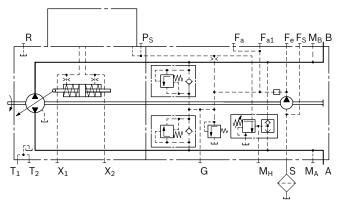
### Determining the operating characteristics

Flow 
$$q_v = \frac{V_g \bullet n \bullet \eta_v}{1000} \qquad [L/min] \qquad V_g \qquad = \text{Displacement per revolution in cm}^3$$
 
$$\Delta p \qquad = \text{Differential pressure in bar}$$
 
$$T = \frac{V_g \bullet \Delta p}{20 \bullet \pi \bullet \eta_{mh}} \qquad [Nm] \qquad n \qquad = \text{Speed in rpm}$$
 
$$\eta_v \qquad = \text{Volumetric efficiency}$$
 
$$Power \qquad P = \frac{2 \pi \bullet T \bullet n}{60000} = \frac{q_v \bullet \Delta p}{600 \bullet \eta_t} \qquad [kW] \qquad \eta_{mh} \qquad = \text{Mechanical-hydraulic efficiency}$$
 
$$\eta_t \qquad = \text{Total efficiency} (\eta_t = \eta_v \bullet \eta_{mh})$$

### NV - Version without control module

The mounting surface for the control module is machined and is sealed with the standard seal for control modules and a cover plate. This version is ready for retrofitting to control modules (HD, HW, EP, EZ). When used directly for "DA" control and in combinations with "DA" control, the appropriate adjustments must be made to the spring assembly of the control cylinder and control plate.

#### Standard version1)



 $_{1)}$  Sizes 28 and 250 without ports  $F_{a1}$  and  $F_{S}$ 

# DG - Hydraulic control, direct controlled

With the direct hydraulic control (DG), the output flow of the pump is controlled by a hydraulic control pressure, applied directly to the stroking piston through either port  $X_1$  or  $X_2$ .

Flow direction is determined by which control pressure port is pressurized (refer to table below).

Pump displacement is infinitely variable and proportional to the applied control pressure, but is also influenced by system pressure and pump drive speed.

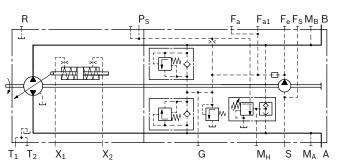
The pressure cut-off and the DA control valve only become effective if the pilot control device used for controlling the DG control is supplied from port P<sub>S</sub>.

Maximum permissible control pressure: 40 bar

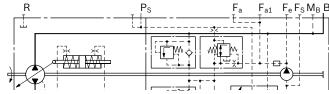
Use of the DG control requires a review of the engine and vehicle parameters to ensure that the pump is set up correctly. We recommend that all DG applications be reviewed by a Bosch Rexroth application engineer.

If the pump is also equipped with a DA control valve (see page 17), automotive operation is possible for travel drives.

#### Standard version1)



#### Version with DA control valve1)



 $^{1)}$  Sizes 28 and 250 without ports  $F_{a1}$  and  $F_{S}$ 

# Correlation Direction of rotation – Control – Flow direction

		Size	Control pressure	Flow direction	Operating pressure
		28 to 56	X <sub>1</sub>	A to B	M <sub>B</sub>
Ē	CW	26 10 50	$X_2$	B to A	M <sub>A</sub>
tatio	Ö	71 to 250	X <sub>1</sub>	B to A	M <sub>A</sub>
of ro			$X_2$	A to B	M <sub>B</sub>
tion		00 - 50	X <sub>1</sub>	B to A	M <sub>A</sub>
Direction of rotation	ccw	28 to 56	$X_2$	A to B	M <sub>B</sub>
	22	71 to 250	X <sub>1</sub>	A to B	M <sub>B</sub>
		71 10 250	X <sub>2</sub>	B to A	M <sub>A</sub>

# HD - Proportional control hydraulic, pilot-pressure related

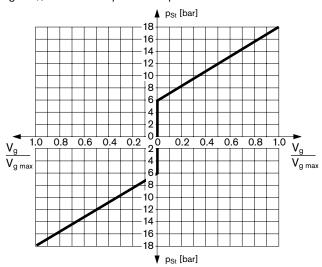
The output flow of the pump is infinitely variable between 0 to 100 %, proportional to the difference in pilot pressure applied to the two control ports  $(Y_1 \text{ and } Y_2)$ .

The pilot signal, coming from an external source, is a pressure signal. Flow is negligible, as the pilot signal acts only on the spool of the control valve.

This valve spool then directs control oil into and out of the stroking cylinder to adjust pump displacement as required.

A feedback lever, connected to the stroking piston maintains the pump flow for any given pilot signal within the control range.

If the pump is also equipped with a DA control valve (see page 17), automotive operation is possible for travel drives.



 $V_g$  = Displacement at  $p_{St}$  $V_{g max}$  = Displacement at  $p_{St}$  = 18 bar

Pilot signal  $p_{St} = 6$  to 18 bar (at port  $Y_1, Y_2$ )

Beginning of control at 6 bar

End of control at 18 bar (maximum displacement V<sub>g max</sub>)

#### Note:

In the neutral position, the HD control module must be vented to reservoir via the external pilot control device.

#### Note

# The spring return feature in the control module is not a safety device

The control module can stick in an undefined position by internal contamination (contaminated hydraulic fluid, abrasion or residual contamination from system components). As a result, the control will no longer respond correctly to the operator's commands.

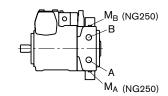
Check whether the application on your machine requires additional safety measures, in order to bring the driven actuator into a controlled and safe position (immediate stop). If necessary, make sure these are properly implemented.

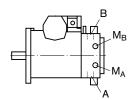
# Correlation Direction of rotation – Control – Flow direction

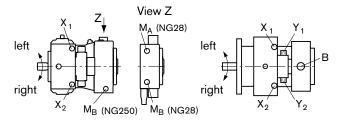
		Size	Pilot signal	Control pressure	Flow direction	Operating pressure
		28 to 56	Y <sub>1</sub>	X <sub>1</sub>	A to B	M <sub>B</sub>
Ē	CW	26 10 50	Y <sub>2</sub>	$X_2$	B to A	M <sub>A</sub>
Direction of rotation	Ó	71 to 250	Y <sub>1</sub>	X <sub>1</sub>	B to A	M <sub>A</sub>
of ro			Y <sub>2</sub>	$X_2$	A to B	M <sub>B</sub>
tion		00 +- 50	Y <sub>1</sub>	X <sub>1</sub>	B to A	M <sub>A</sub>
irec	ccw	28 to 56	Y <sub>2</sub>	$X_2$	A to B	M <sub>B</sub>
Δ	22	71 to 250	Y <sub>1</sub>	X <sub>1</sub>	A to B	M <sub>B</sub>
		71 10 250	Y <sub>2</sub>	$X_2$	B to A	M <sub>A</sub>

Sizes 28, 250

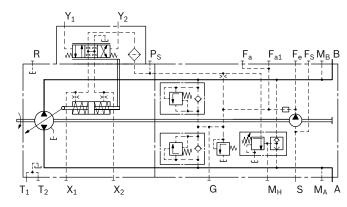
Sizes 40 to 180



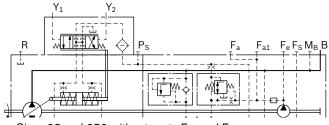




### Standard version1)



#### Version with DA control valve1)



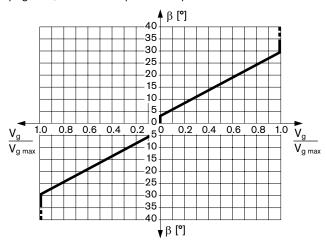
 $_{1)}$  Sizes 28 and 250 without ports  $F_{a1}$  and  $F_{S}$ 

# HW - Proportional control hydraulic, mechanical servo

The output flow of the pump is infinitely variable between 0 to 100 %, proportional to the swivel angle of the control lever between 0° and  $\pm 29$ ° from the spring centered zero flow position.

A feedback lever, connected to the stroking piston maintains the pump flow for any given position of the control lever between 0° and 29°.

If the pump is also equipped with a DA control valve (see page 17), automotive operation is possible for travel drives.



Swivel angle  $\beta$  at the control lever for pump displacement change:

Beginning of control at  $\beta = 3^{\circ}$ 

End of control at  $\beta = 29^{\circ}$  (maximum displacement  $V_{q max}$ )

Mechanical stop for  $\beta$ :

Size 28 to 71	±40°
Size 90 to 250	 ±35°

The maximum required torque at the lever is 170 Ncm. To prevent damage to the HW control module, a positive mechanical stop must be provided for the HW control lever.

#### Note:

Spring centering enables the pump, depending on pressure and speed, to move automatically to the neutral position  $(V_g=0)$  as soon as there is no longer any torque on the control lever of the HW control module (regardless of deflection angle).

### Variation: neutral position switch

The switch contact in the neutral position switch is closed when the control lever on the HW control module is in its neutral position. The switch opens when the control lever is moved out of neutral in either direction.

Thus, the neutral position switch provides a monitoring function for drive units that require the pump to be in the neutral position during certain operating conditions (e. g. starting diesel engines).

Technical data, neutral position switch							
Load capacity	20 A (continuous), w/o switching operating						
Switching capacity	15 A / 32 V (resistive load)						
	4 A / 32 V (inductive load)						
Connector design	DEUTSCH DT04-2P-EP04 (mating connector, see page 62)						

# Correlation Direction of rotation - Control - Flow direction

		Size	Lever direction	Control pressure	Flow direction	Operating pressure
		28 to 56	а	X <sub>2</sub>	B to A	M <sub>A</sub>
Ē	CW	26 10 56	b	X <sub>1</sub>	A to B	M <sub>B</sub>
tatio	Ó		a	$X_2$	A to B	M <sub>B</sub>
of ro		71 to 250	b	X <sub>1</sub>	B to A	M <sub>A</sub>
tion		00.1 50	a	$X_2$	A to B	M <sub>B</sub>
Direction of rotation	ccw	28 to 56	b	X <sub>1</sub>	B to A	M <sub>A</sub>
	9	71 +- 050	a	X <sub>2</sub>	B to A	M <sub>A</sub>
		71 to 250	b	X <sub>1</sub>	A to B	M <sub>B</sub>

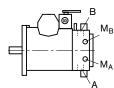
Sizes 28, 250

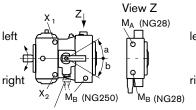
M<sub>B</sub> (NG250)

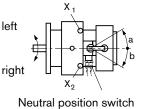
A

M<sub>A</sub> (NG250)

Sizes 40 to 180

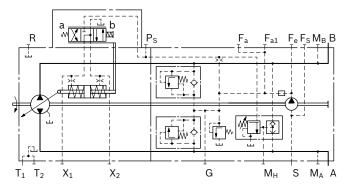




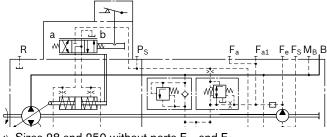


Neutral position switch

#### Standard version1)



Version with DA control valve and neutral position switch<sup>1)</sup>



 $_{1)}$  Sizes 28 and 250 without ports  $F_{a1}$  and  $F_{S}$ 

# EP - Proportional control electric

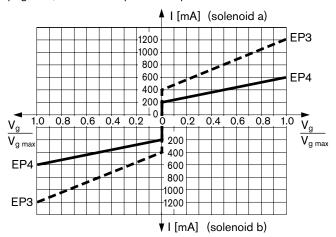
The output flow of the pump is infinitely variable between 0 to 100 %, proportional to the electrical current supplied to solenoid a or b.

The electrical energy is converted into a force acting on the spool of the control valve.

This valve spool then directs control oil into and out of the stroking cylinder to adjust pump displacement as required.

A feedback lever, connected to the stroking piston maintains the pump flow for any given current within the control range.

If the pump is also equipped with a DA control valve (see page 17), automotive operation is possible for travel drives.



#### Technical data, solenoid

	EP3	EP4
Voltage	12 V (±20 %)	24 V (±20 %)
Control current		
Beginning of control at $V_g = 0$	400 mA	200 mA
End of control at V <sub>g max</sub>	1200 mA	600 mA
Limiting current	1.54 A	0.77 A
Nominal resistance (at 20 °C)	5.5 Ω	22.7 Ω
Dither frequency	100 Hz	100 Hz
Duty cycle	100 %	100 %

Type of protection see connector design page 62

The following electronic controllers and amplifiers are available for controlling the proportional solenoids:

<ul> <li>BODAS controller RC</li> </ul>	
Series 20	RE 95200
Series 21	RE 95201
Series 22	RE 95202
Series 30	RE 95203, RE 95204
and application software	
- Analog amplifier RA	RE 95230

Further information can also be found on the Internet at www.boschrexroth.com/mobile-electronics.

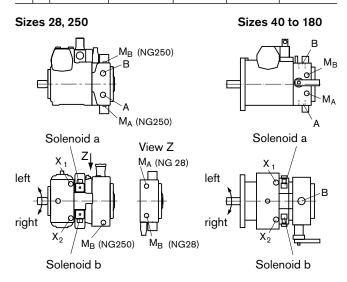
#### Note

# The spring return feature in the control module is not a safety device

The control module can stick in an undefined position by internal contamination (contaminated hydraulic fluid, abrasion or residual contamination from system components). As a result, the control will no longer respond correctly to the operator's commands.

Check whether the application on your machine requires additional safety measures, in order to bring the driven actuator into a controlled and safe position (immediate stop). If necessary, make sure these are properly implemented.

#### Correlation Direction of rotation - Control - Flow direction Size Actuation Control Flow Operating of solenoid pressure direction pressure $X_1$ A to B $M_B$ 28 to 56 b $\chi_2$ B to A $M_A$ Direction of rotation Š $X_1$ B to A $M_A$ 71 to 250 h $X_2$ A to B $\mathsf{M}_\mathsf{B}$ X<sub>1</sub> B to A $M_A$ 28 to 56 b $X_2$ A to B $M_{B}$ $X_1$ A to B $M_{\mathsf{B}}$ 71 to 250 $X_2$ B to A $M_A$



#### Standard

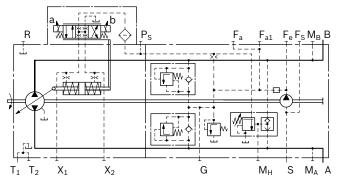
Proportional solenoid without manual override.

### On request

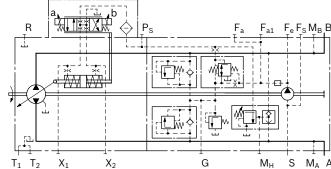
Proportional solenoid with manual override and spring return.

# EP - Proportional control electric

#### Standard version1)



### Version with DA control valve1)



 $_{1)}$  Sizes 28 and 250 without ports  $F_{a1}$  and  $F_{S}$ 

# EZ - Two-point control electric

By energizing either switching solenoid a or b, internal control pressure is connected directly to the stroking piston and the pump swivels to maximum displacement. With the EZ control, pump flow is switchable between  $V_g = 0$  and  $V_{g\ max}$ . Flow direction is determined by which solenoid is energized.

### Technical data, solenoid

	EZ1	EZ2
Voltage	12 V (±20 %)	24 V (±20 %)
Neutral position $V_g = 0$	de-energized	de-energized
Displacement V <sub>g max</sub>	Energized	Energized
Nominal resistance (at 20 °C)	5.5 Ω	21.7 Ω
Nominal power	26.2 W	26.5 W
Minimum required current	1.32 A	0.67 A
Duty cycle	100 %	100 %

Type of protection see connector design page 62

#### Standard

Switching solenoid without manual override.

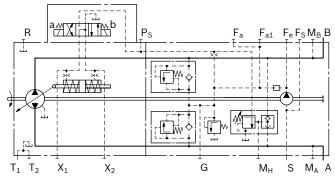
#### On request

Switching solenoid with manual override and spring return.

# Correlation Direction of rotation – Control – Flow direction

		Size	Actuation of solenoid	Control pressure	Flow direction	Operating pressure
		28 to 56	a	$X_2$	B to A	M <sub>A</sub>
_	CW	26 10 56	b	X <sub>1</sub>	A to B	M <sub>B</sub>
tatio	71 to 050	a	$X_2$	A to B	M <sub>B</sub>	
of ro	전 71 to 250	b	X <sub>1</sub>	B to A	M <sub>A</sub>	
Direction of rotation of 28 to 5	00 to 56	a	$X_2$	A to B	M <sub>B</sub>	
irec	ccw	28 to 56	b	X <sub>1</sub>	B to A	M <sub>A</sub>
	22	71 to 250	a	$X_2$	B to A	M <sub>A</sub>
		71 10 250	b	X <sub>1</sub>	A to B	M <sub>B</sub>

### Standard version1)



 $_{1)}$  Sizes 28 and 250 without ports  $F_{a1}$  and  $F_{S}$ 

# DA - Automatic control speed-related

The DA closed loop control is an engine speed-dependent system for travel drives. The built-in DA control valve generates a control pressure which is proportional to pump (engine) drive speed. This control pressure is directed to the stroking cylinder of the pump by a solenoid actuated 4/3-way directional valve. The pump displacement is infinitely variable in each flow direction and is influenced by both pump drive speed and system pressure. The flow direction (e. g. machine moving forward or backward) is determined by either solenoid a or b being activated.

Increasing pump drive speed generates a higher control pressure from the DA control valve, with a subsequent increase in pump flow.

Depending on the selected pump operating characteristics, increasing system pressure (e. g. machine load) causes the pump to swivel back towards a smaller displacement. Engine overload protection (anti-stall) is achieved by the combination of this pressure-related pump de-stroking, and the reduction of control pressure as the engine speed drops.

Any additional power requirement, e. g. for hydraulic functions from attachments, could cause the engine speed to drop further. This would cause a further reduction in control pressure and thus of pump displacement. Automatic power distribution and full exploitation of the available power are achieved in this way, both for the travel drive and for the implement hydraulics, with priority given to the implement hydraulics.

Various override options are available for the DA control function to allow controlled operation of the implement hydraulics with high rpm at reduced vehicle speed.

The DA control valve can also be used in pumps with EP, DG, HW and HD control modules to protect the combustion engine against overload.

DA closed loop control is only suitable for certain types of drive systems and requires review of the engine and vehicle parameters to ensure that the pump is used correctly and that machine operation is safe and efficient. We recommend that all DA applications be reviewed by a Bosch Rexroth application engineer.

### Technical data, solenoid

	DA1	DA2
Voltage	12 V (±20 %)	24 V (±20 %)
Neutral position V <sub>g</sub> = 0	de-energized	de-energized
Displacement V <sub>g max</sub>	Energized	Energized
Nominal resistance (at 20 °C)	5.5 Ω	21.7 Ω
Nominal power	26.2 W	26.5 W
Minimum required current	1.32 A	0.67 A
Duty cycle	100 %	100 %
Type of protection see connection	ctor design page	62

#### Standard

Switching solenoid without manual override.

#### On request

Switching solenoid with manual override and spring return.

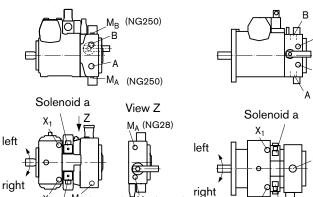
# Correlation Direction of rotation - Control - Flow direction

		Size	Actuation of solenoid	Control pressure	Flow direction	Operating pressure
		00 to 56	a	$X_2$	B to A	M <sub>A</sub>
Ē	ion	28 to 56	b	X <sub>1</sub>	A to B	M <sub>B</sub>
tatio	ن	71 to 250	a	$X_2$	A to B	M <sub>B</sub>
Direction of rotation	5 71 10 2	71 10 250	b	X <sub>1</sub>	B to A	M <sub>A</sub>
ion	28 to 56	а	$X_2$	A to B	M <sub>B</sub>	
irec	ccw	<b>I</b>	b	X <sub>1</sub>	B to A	M <sub>A</sub>
		E4 1 0E0	а	$X_2$	B to A	M <sub>A</sub>
		71 to 250	b	X <sub>1</sub>	A to B	M <sub>B</sub>

Sizes 28, 250

Sizes 40 to 180

Solenoid b

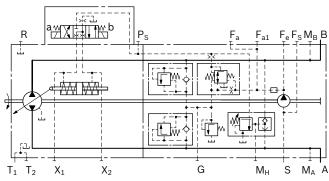


M<sub>B</sub> (NG28)

#### DA control valve fixed setting, DA1D2/DA2D21)

M<sub>B</sub> (NG250)

Solenoid b



1) Sizes 28 and 250 without ports Fa1 and FS

# DA - Automatic control speed-related

#### Function and control of DA control valves

#### DA control valve fixed setting (2)

Control pressure is generated in relation to drive speed. When ordering, state in plain text: start of control (set at factory).

#### DA control valve mechanically adjustable with position lever (3)

Control pressure is generated in relation to drive speed. When ordering, state in plain text: start of control (set at factory).

Any reduction of the control pressure possible, independently of the drive speed, through mechanical actuation of the position lever (inch function).

The maximum permissible actuation torque at the position lever is  $T_{max} = 4 \text{ Nm}$ .

Maximum angle of rotation 70°, lever position: any.

#### Version 3R

Actuating direction of the position lever: right

#### Version 3L

Actuating direction of the position lever: left

#### DA control valve fixed setting and braking inch valve mounted (4, 8)

(only for pumps with DA control module)

- Version with throttle valve size 28, 40, 56, 71
- Version with pressure reducing valve size 90, 125, 180, 250

Any reduction of the control pressure possible, independently of the drive speed via hydraulic control (port Z).

#### Version 4:

Control at port Z by means of brake fluid according to ISO 4925 (no mineral oil), from the vehicle braking system (hydraulically linked with the service brake).

#### Version 8:

Control at port Z by means of brake fluid based on mineral oil.

#### DA control valve fixed setting, ports for pilot control device as inch valve (7)

Any reduction of the pilot pressure possible, independently of the drive speed is achieved by the mechanical actuation of the pilot control device.

The pilot control device is installed separately from the pump (for example in the driver's cabin) and connected to the pump by two hydraulic control lines via ports P<sub>S</sub> and Y.

A suitable pilot control device must be ordered separately and is not included in the delivery contents.

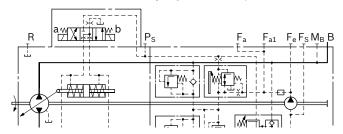
Detailed information is available from our sales department and on the Internet at www.boschrexroth.com/da-control. Use our computer program to work out the input design that meets your needs. All DA applications must be approved by a Bosch Rexroth application engineer.

Note: Rotary inch valves, see page 63.

#### Schematics1):

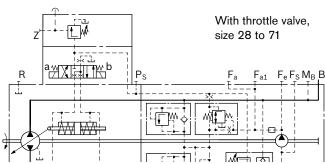
#### DA1D3/DA2D3

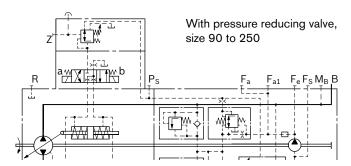
DA control valve mechanically adjustable with position lever



#### DA1D4/DA2D4

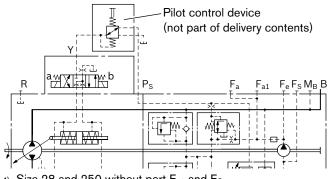
DA control valve fixed setting, with hydraulic inch valve





### DA1D7/DA2D7

DA control valve fixed setting, with separately attached pilot control device as inch valve



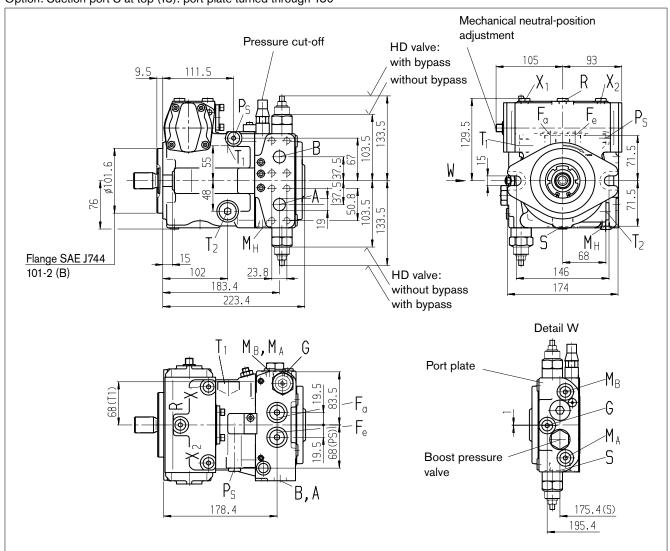
 $^{1)}$  Size 28 and 250 without port  $F_{a1}$  and  $F_{S}$ 

Before finalizing your design, request a binding installation drawing. Dimensions in mm.

### NV - Version without control module

Standard: Suction port S at bottom (10)

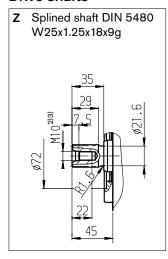
Option: Suction port S at top (13): port plate turned through 180°

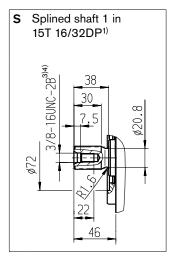


Before finalizing your design, request a binding installation drawing. Dimensions in mm.

### Dimensions size 28

#### **Drive shafts**





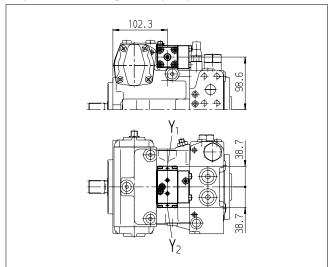
#### **Ports**

Designation	Port for	Standard	Size <sup>3)</sup>	Maximum pressure [bar] <sup>5)</sup>	State <sup>11)</sup>
A, B	Service line Fastening thread A/B	SAE J518 <sup>6)</sup> DIN 13	3/4 in M10 x 1.5; 17 deep	450	0
S	Suction line	DIN 3852 <sup>9)</sup>	M33 x 2; 18 deep	5	O <sup>7)</sup>
T <sub>1</sub>	Drain line	DIN 3852 <sup>9)</sup>	M22 x 1.5; 14 deep	3	O <sub>8)</sub>
T <sub>2</sub>	Drain line	DIN 3852 <sup>9)</sup>	M22 x 1.5; 14 deep	3	X <sub>8)</sub>
R	Air bleed	DIN 3852 <sup>9)</sup>	M12 x 1.5; 12 deep	3	Χ
X <sub>1</sub> , X <sub>2</sub>	Control pressure (upstream of orifice)	DIN 3852 <sup>9)</sup>	M12 x 1.5; 12 deep	40	Χ
X <sub>1</sub> , X <sub>2</sub>	Control pressure (upstream of orifice, DG only)	DIN 3852 <sup>9)</sup>	M12 x 1.5; 12 deep	40	0
X <sub>3</sub> , X <sub>4</sub> <sup>10)</sup>	Stroking chamber pressure	DIN 3852 <sup>9)</sup>	M12 x 1.5; 12 deep	40	Χ
G	Boost pressure	DIN 3852 <sup>9)</sup>	M12 x 1.5; 12 deep	40	Χ
Ps	Pilot pressure	DIN 3852 <sup>9)</sup>	M14 x 1.5; 12 deep	40	Χ
Ps	Pilot pressure (DA7 only)	DIN 3852 <sup>9)</sup>	M14 x 1.5; 12 deep	40	0
Υ	Pilot pressure (DA7 only)	DIN 3852 <sup>9)</sup>	M14 x 1.5; 12 deep	40	0
M <sub>A</sub> , M <sub>B</sub>	Measuring pressure A, B	DIN 3852 <sup>9)</sup>	M12 x 1.5; 12 deep	450	Χ
M <sub>H</sub>	Measuring high pressure	DIN 3852 <sup>9)</sup>	M12 x 1.5; 12 deep	450	Χ
Fa	Boost pressure inlet	DIN 3852 <sup>9)</sup>	M18 x 1.5; 12 deep	40	Χ
F <sub>e</sub>	Boost pressure outlet	DIN 3852 <sup>9)</sup>	M18 x 1.5; 12 deep	40	Χ
Y <sub>1</sub> , Y <sub>2</sub>	Pilot signal (HD only)	DIN 3852 <sup>9)</sup>	M14 x 1.5; 12 deep	40	0
Z	Inch signal (DA4 and 8 only)	DIN 3852 <sup>9)</sup>	M10 x 1; 8 deep	40	Χ

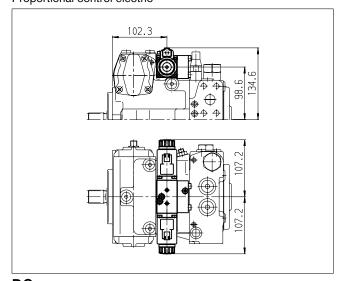
- 1) ANSI B92.1a, 30° pressure angle, flat root, side fit, tolerance class 5
- 2) Center bore according to DIN 332 (thread according to DIN 13)
- 3) Observe the general instructions on page 68 for the maximum tightening torques.
- 4) Thread according to ASME B1.1
- 5) Momentary pressure spikes may occur depending on the application. Keep this in mind when selecting measuring devices and fittings.
- 6) Only dimensions according to SAE J518, metric fastening thread is a deviation from standard.
- 7) Plugged with external supply.
- 8) Depending on installation position, T<sub>1</sub> or T<sub>2</sub> must be connected (see also installation instructions on pages 65 and 66).
- 9) The spot face can be deeper than specified in the appropriate standard.
- 10) Optional, see page 56
- 11) O = Must be connected (plugged on delivery)
  - X = Plugged (in normal operation)

HD

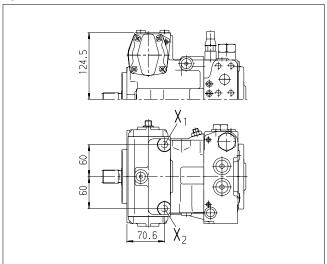
Proportional control hydraulic, pilot-pressure related



**EP** Proportional control electric



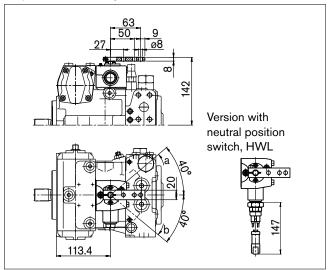
**DG**Hydraulic control, direct controlled



Before finalizing your design, request a binding installation drawing. Dimensions in mm.

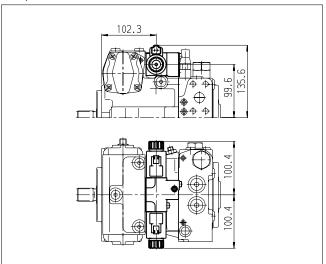
### HW

Proportional control hydraulic, mechanical servo



### ΕZ

Two-point control electric

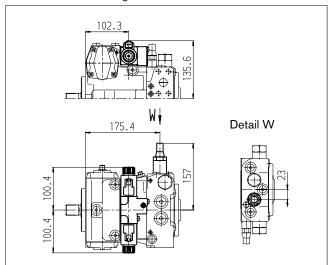


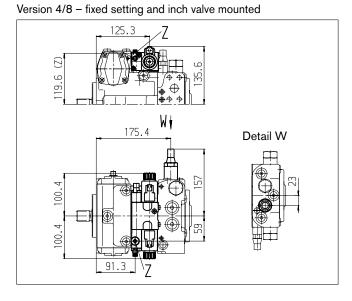
Before finalizing your design, request a binding installation drawing. Dimensions in mm.

# Dimensions size 28

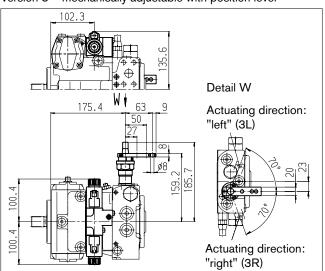
### DA - control valve

Version 2 - fixed setting

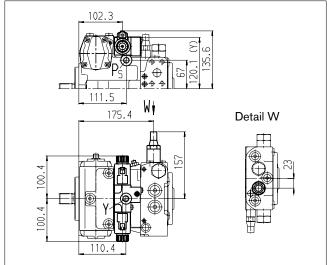




Version 3 - mechanically adjustable with position lever



Version 7 - fixed setting and ports for pilot control device

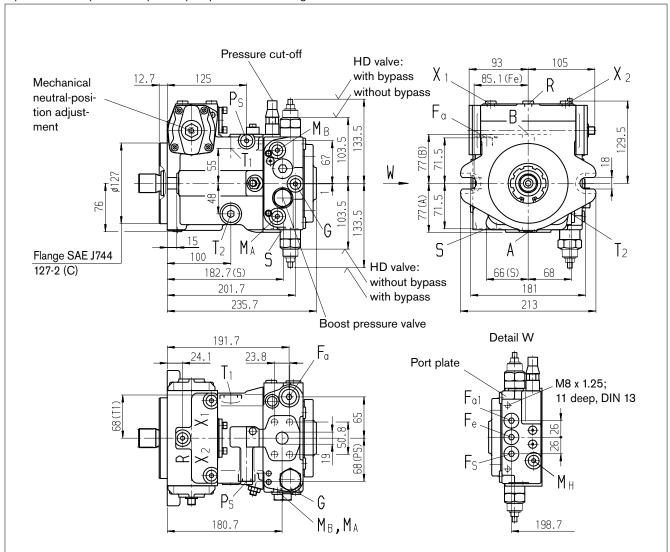


Before finalizing your design, request a binding installation drawing. Dimensions in mm.

### NV - Version without control module

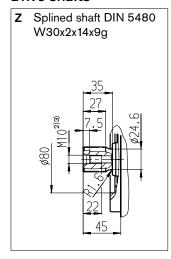
Standard: Suction port S at bottom (02)

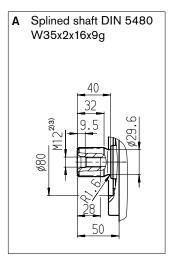
Option: Suction port S at top (03): port plate turned through 180°

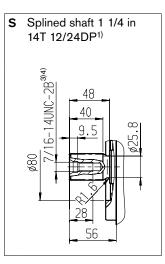


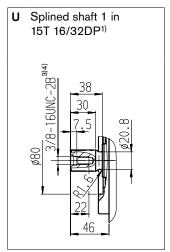
# Before finalizing your design, request a binding installation drawing. Dimensions in mm.

#### **Drive shafts**









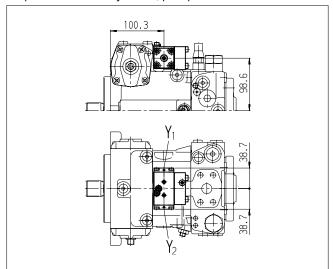
#### **Ports**

Designation	Port for	Standard	Size <sup>3)</sup>	Maximum pressure [bar] <sup>5)</sup>	State <sup>11)</sup>
A, B	Service line Fastening thread A/B	SAE J518 <sup>6)</sup> DIN 13	3/4 in M10 x 1.5; 17 deep	450	0
S	Suction line	DIN 3852 <sup>9)</sup>	M33 x 2; 18 deep	5	O <sup>7)</sup>
T <sub>1</sub>	Drain line	DIN 3852 <sup>9)</sup>	M22 x 1.5; 14 deep	3	O <sub>8)</sub>
T <sub>2</sub>	Drain line	DIN 3852 <sup>9)</sup>	M22 x 1.5; 14 deep	3	X <sub>8)</sub>
R	Air bleed	DIN 3852 <sup>9)</sup>	M12 x 1.5; 12 deep	3	Χ
X <sub>1</sub> , X <sub>2</sub>	Control pressure (upstream of orifice)	DIN 3852 <sup>9)</sup>	M12 x 1.5; 12 deep	40	Χ
X <sub>1</sub> , X <sub>2</sub>	Control pressure (upstream of orifice, DG only)	DIN 3852 <sup>9)</sup>	M12 x 1.5; 12 deep	40	0
X <sub>3</sub> , X <sub>4</sub> <sup>10)</sup>	Stroking chamber pressure	DIN 3852 <sup>9)</sup>	M12 x 1.5; 12 deep	40	Х
G	Boost pressure	DIN 3852 <sup>9)</sup>	M12 x 1.5; 12 deep	40	Χ
Ps	Pilot pressure	DIN 3852 <sup>9)</sup>	M14 x 1.5; 12 deep	40	Χ
Ps	Pilot pressure (DA7 only)	DIN 3852 <sup>9)</sup>	M14 x 1.5; 12 deep	40	0
Υ	Pilot pressure (DA7 only)	DIN 3852 <sup>9)</sup>	M14 x 1.5; 12 deep	40	0
$M_A$ , $M_B$	Measuring pressure A, B	DIN 3852 <sup>9)</sup>	M12 x 1.5; 12 deep	450	Χ
$M_H$	Measuring high pressure	DIN 3852 <sup>9)</sup>	M12 x 1.5; 12 deep	450	X
Fa	Boost pressure inlet	DIN 3852 <sup>9)</sup>	M18 x 1.5; 12 deep	40	Χ
F <sub>a1</sub>	Boost pressure, inlet (mountable filter)	DIN 3852 <sup>9)</sup>	M18 x 1.5; 12 deep	40	Χ
F <sub>e</sub>	Boost pressure outlet	DIN 3852 <sup>9)</sup>	M18 x 1.5; 12 deep	40	Χ
F <sub>S</sub>	Line from filter to suction line (cold start)	DIN 3852 <sup>9)</sup>	M18 x 1.5; 12 deep	40	Х
Y <sub>1</sub> , Y <sub>2</sub>	Pilot signal (HD only)	DIN 3852 <sup>9)</sup>	M14 x 1.5; 12 deep	40	0
Z	Inch signal (DA4 and 8 only)	DIN 3852 <sup>9)</sup>	M10 x 1; 8 deep	40	Χ

- 1) ANSI B92.1a, 30° pressure angle, flat root, side fit, tolerance class 5
- 2) Center bore according to DIN 332 (thread according to DIN 13)
- 3) Observe the general instructions on page 68 for the maximum tightening torques.
- 4) Thread according to ASME B1.1
- 5) Momentary pressure spikes may occur depending on the application. Keep this in mind when selecting measuring devices and fittings.
- 6) Only dimensions according to SAE J518, metric fastening thread is a deviation from standard.
- 7) Plugged with external supply.
- 8) Depending on installation position, T<sub>1</sub> or T<sub>2</sub> must be connected (see also installation instructions on pages 65 and 66).
- 9) The spot face can be deeper than specified in the appropriate standard.
- 10) Optional, see page 56
- 11) O = Must be connected (plugged on delivery)
  - X = Plugged (in normal operation)

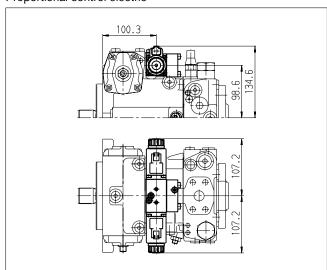
HD

Proportional control hydraulic, pilot-pressure related



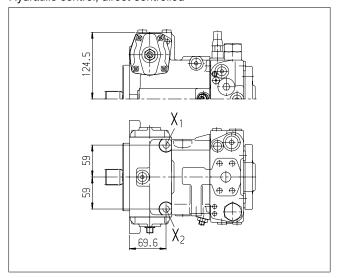
ΕP

Proportional control electric



DG

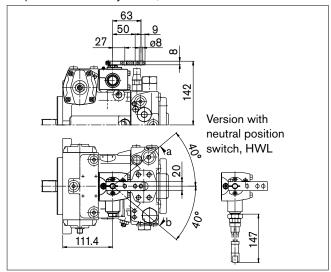
Hydraulic control, direct controlled



Before finalizing your design, request a binding installation drawing. Dimensions in mm.

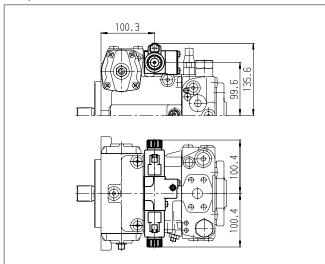
### HW

Proportional control hydraulic, mechanical servo



### ΕZ

Two-point control electric

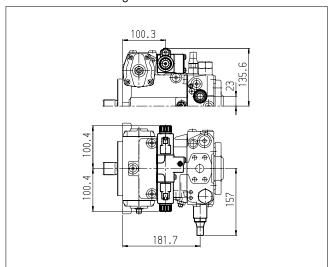


Before finalizing your design, request a binding installation drawing. Dimensions in mm.

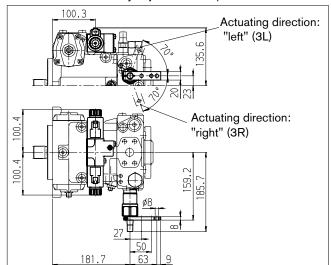
# Dimensions size 40

### DA - control valve

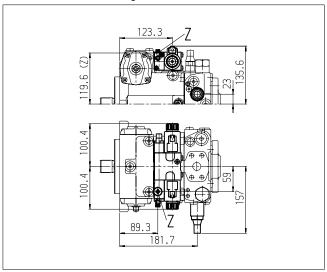
Version 2 - fixed setting



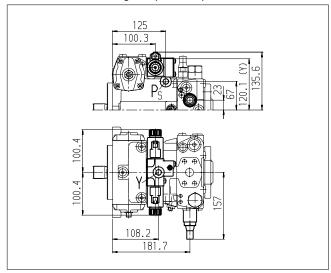
Version 3 - mechanically adjustable with position lever



Version 4/8 - fixed setting and inch valve mounted



Version 7 - fixed setting and ports for pilot control device

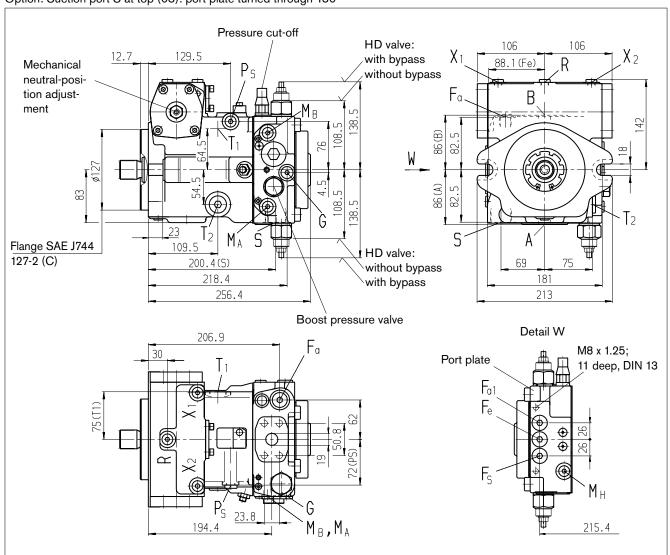


# Before finalizing your design, request a binding installation drawing. Dimensions in mm.

### NV - Version without control module

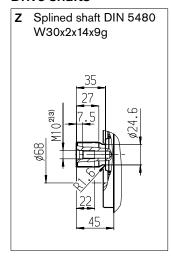
Standard: Suction port S at bottom (02)

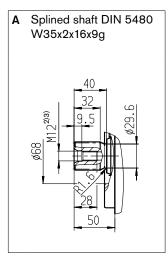
Option: Suction port S at top (03): port plate turned through 180°

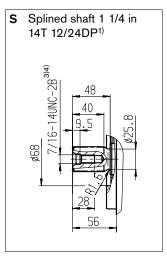


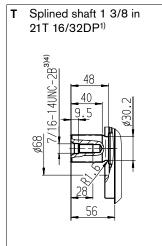
# Before finalizing your design, request a binding installation drawing. Dimensions in mm.

#### **Drive shafts**









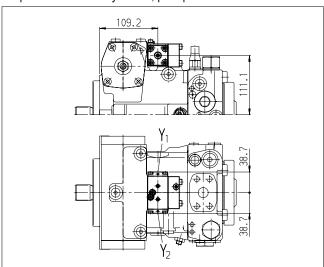
#### **Ports**

Designation	Port for	Standard	Size <sup>3)</sup>	Maximum pressure [bar] <sup>5)</sup>	State <sup>11)</sup>
A, B	Service line Fastening thread A/B	SAE J518 <sup>6)</sup> DIN 13	3/4 in M10 x 1.5; 17 deep	450	0
S	Suction line	DIN 3852 <sup>9)</sup>	M33 x 2; 18 deep	5	O <sup>7)</sup>
T <sub>1</sub>	Drain line	DIN 3852 <sup>9)</sup>	M22 x 1.5; 14 deep	3	O <sub>8</sub> )
T <sub>2</sub>	Drain line	DIN 3852 <sup>9)</sup>	M22 x 1.5; 14 deep	3	X <sub>8)</sub>
R	Air bleed	DIN 3852 <sup>9)</sup>	M12 x 1.5; 12 deep	3	Χ
X <sub>1</sub> , X <sub>2</sub>	Control pressure (upstream of orifice)	DIN 3852 <sup>9)</sup>	M12 x 1.5; 12 deep	40	Х
X <sub>1</sub> , X <sub>2</sub>	Control pressure (upstream of orifice, DG only)	DIN 3852 <sup>9)</sup>	M12 x 1.5; 12 deep	40	0
X <sub>3,</sub> X <sub>4</sub> <sup>10)</sup>	Stroking chamber pressure	DIN 3852 <sup>9)</sup>	M12 x 1.5; 12 deep	40	Χ
G P <sub>S</sub>	Boost pressure	DIN 3852 <sup>9)</sup>	M14 x 1.5; 12 deep	40	Χ
Ps	Pilot pressure	DIN 3852 <sup>9)</sup>	M14 x 1.5; 12 deep	40	Χ
P <sub>S</sub> Y	Pilot pressure (DA7 only)	DIN 3852 <sup>9)</sup>	M14 x 1.5; 12 deep	40	0
Υ	Pilot pressure (DA7 only)	DIN 3852 <sup>9)</sup>	M14 x 1.5; 12 deep	40	0
M <sub>A</sub> , M <sub>B</sub>	Measuring pressure A, B	DIN 3852 <sup>9)</sup>	M12 x 1.5; 12 deep	450	X
M <sub>H</sub>	Measuring high pressure	DIN 3852 <sup>9)</sup>	M12 x 1.5; 12 deep	450	Χ
Fa	Boost pressure inlet	DIN 3852 <sup>9)</sup>	M18 x 1.5; 12 deep	40	Χ
F <sub>a1</sub>	Boost pressure, inlet (mountable filter)	DIN 3852 <sup>9)</sup>	M18 x 1.5; 12 deep	40	Χ
F <sub>e</sub>	Boost pressure outlet	DIN 3852 <sup>9)</sup>	M18 x 1.5; 12 deep	40	Χ
F <sub>S</sub>	Line from filter to suction line (cold start)	DIN 3852 <sup>9)</sup>	M18 x 1.5; 12 deep	40	Х
Y <sub>1</sub> , Y <sub>2</sub>	Pilot signal (HD only)	DIN 3852 <sup>9)</sup>	M14 x 1.5; 12 deep	40	0
Z	Inch signal (DA4 and 8 only)	DIN 3852 <sup>9)</sup>	M10 x 1; 8 deep	40	Χ

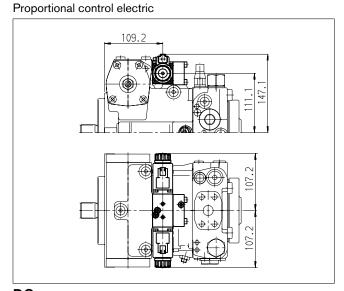
- 1) ANSI B92.1a, 30° pressure angle, flat root, side fit, tolerance class 5
- 2) Center bore according to DIN 332 (thread according to DIN 13)
- 3) Observe the general instructions on page 68 for the maximum tightening torques.
- 4) Thread according to ASME B1.1
- 5) Momentary pressure spikes may occur depending on the application. Keep this in mind when selecting measuring devices and fittings.
- 6) Only dimensions according to SAE J518, metric fastening thread is a deviation from standard.
- 7) Plugged with external supply.
- 8) Depending on installation position, T<sub>1</sub> or T<sub>2</sub> must be connected (see also installation instructions on pages 65 and 66).
- 9) The spot face can be deeper than specified in the appropriate standard.
- 10) Optional, see page 56
- 11) O = Must be connected (plugged on delivery)
  - X = Plugged (in normal operation)

### HD

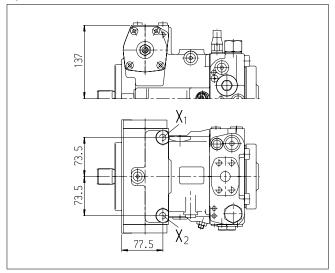
Proportional control hydraulic, pilot-pressure related



**EP** 



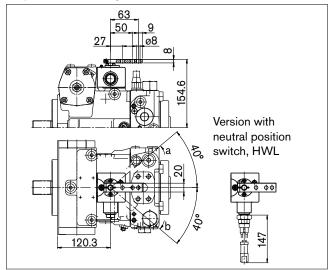
**DG**Hydraulic control, direct controlled



Before finalizing your design, request a binding installation drawing. Dimensions in mm.

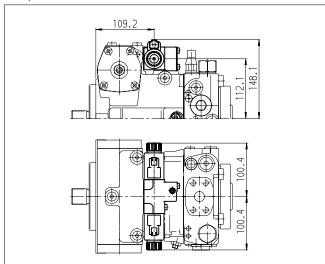
### HW

Proportional control hydraulic, mechanical servo



### ΕZ

Two-point control electric

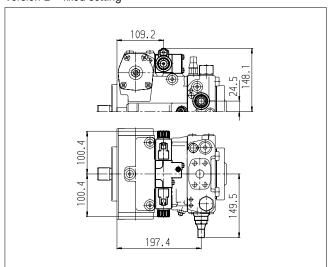


Before finalizing your design, request a binding installation drawing. Dimensions in mm.

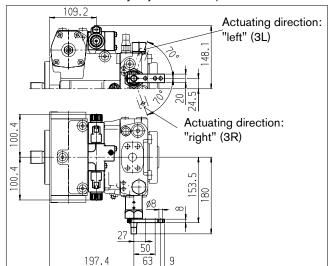
# Dimensions size 56

### DA - control valve

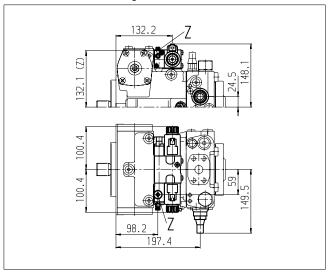
Version 2 - fixed setting



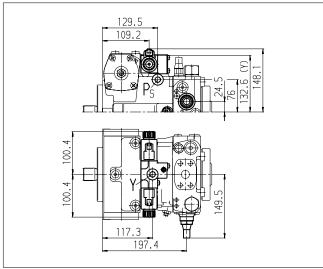
Version 3 - mechanically adjustable with position lever



Version 4/8 - fixed setting and inch valve mounted



Version 7 - fixed setting and ports for pilot control device



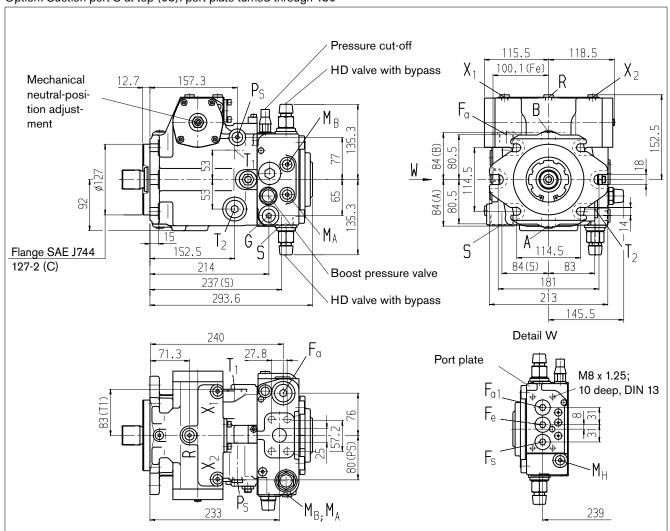
Before finalizing your design, request a binding installation drawing. Dimensions in mm.

# Dimensions size 71

### NV - Version without control module

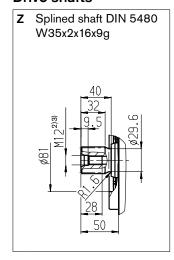
Standard: Suction port S at bottom (02)

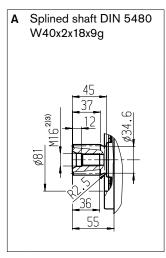
Option: Suction port S at top (03): port plate turned through 180°

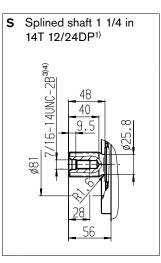


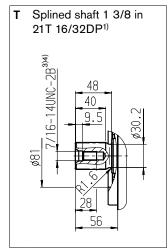
# Before finalizing your design, request a binding installation drawing. Dimensions in mm.

#### **Drive shafts**









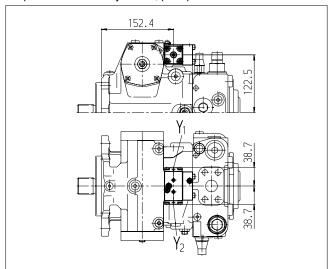
#### **Ports**

Designation	Port for	Standard	Size <sup>3)</sup>	Maximum pressure [bar] <sup>5)</sup>	State <sup>11)</sup>
A, B	Service line Fastening thread A/B	SAE J518 <sup>6)</sup> DIN 13	1 in M12 x 1.75; 17 deep	450	0
S	Suction line	DIN 3852 <sup>9)</sup>	M42 x 2; 20 deep	5	O <sup>7)</sup>
T <sub>1</sub>	Drain line	DIN 38529)	M26 x 1.5; 16 deep	3	O <sub>8</sub> )
T <sub>2</sub>	Drain line	DIN 3852 <sup>9)</sup>	M26 x 1.5; 16 deep	3	X <sub>8)</sub>
R	Air bleed	DIN 3852 <sup>9)</sup>	M12 x 1.5; 12 deep	3	Χ
X <sub>1</sub> , X <sub>2</sub>	Control pressure (upstream of orifice)	DIN 3852 <sup>9)</sup>	M12 x 1.5; 12 deep	40	Х
X <sub>1</sub> , X <sub>2</sub>	Control pressure (upstream of orifice, DG only)	DIN 3852 <sup>9)</sup>	M12 x 1.5; 12 deep	40	0
X <sub>3,</sub> X <sub>4</sub> <sup>10)</sup>	Stroking chamber pressure	DIN 3852 <sup>9)</sup>	M12 x 1.5; 12 deep	40	Χ
G P <sub>S</sub>	Boost pressure	DIN 3852 <sup>9)</sup>	M18 x 1.5; 12 deep	40	Χ
Ps	Pilot pressure	DIN 3852 <sup>9)</sup>	M14 x 1.5; 12 deep	40	Χ
Ps	Pilot pressure (DA7 only)	DIN 3852 <sup>9)</sup>	M14 x 1.5; 12 deep	40	0
Υ	Pilot pressure (DA7 only)	DIN 3852 <sup>9)</sup>	M14 x 1.5; 12 deep	40	0
M <sub>A</sub> , M <sub>B</sub>	Measuring pressure A, B	DIN 3852 <sup>9)</sup>	M12 x 1.5; 12 deep	450	Х
M <sub>H</sub>	Measuring high pressure	DIN 3852 <sup>9)</sup>	M12 x 1.5; 12 deep	450	Х
Fa	Boost pressure inlet	DIN 3852 <sup>9)</sup>	M26 x 1.5; 16 deep	40	Х
F <sub>a1</sub>	Boost pressure, inlet (mountable filter)	DIN 3852 <sup>9)</sup>	M22 x 1.5; 14 deep	40	Х
F <sub>e</sub>	Boost pressure outlet	DIN 3852 <sup>9)</sup>	M22 x 1.5; 14 deep	40	Х
F <sub>S</sub>	Line from filter to suction line (cold start)	DIN 3852 <sup>9)</sup>	M22 x 1.5; 14 deep	40	Х
Y <sub>1</sub> , Y <sub>2</sub>	Pilot signal (HD only)	DIN 3852 <sup>9)</sup>	M14 x 1.5; 8 deep	40	0
Z	Inch signal (DA4 and 8 only)	DIN 3852 <sup>9)</sup>	M10 x 1; 12 deep	40	Х

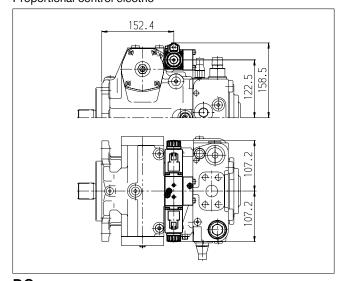
- 1) ANSI B92.1a, 30° pressure angle, flat root, side fit, tolerance class 5
- 2) Center bore according to DIN 332 (thread according to DIN 13)
- 3) Observe the general instructions on page 68 for the maximum tightening torques.
- 4) Thread according to ASME B1.1
- 5) Momentary pressure spikes may occur depending on the application. Keep this in mind when selecting measuring devices and fittings.
- 6) Only dimensions according to SAE J518, metric fastening thread is a deviation from standard.
- 7) Plugged with external supply.
- 8) Depending on installation position, T<sub>1</sub> or T<sub>2</sub> must be connected (see also installation instructions on pages 65 and 66).
- 9) The spot face can be deeper than specified in the appropriate standard.
- 10) Optional, see page 56
- 11) O = Must be connected (plugged on delivery)
  - X = Plugged (in normal operation)

HD

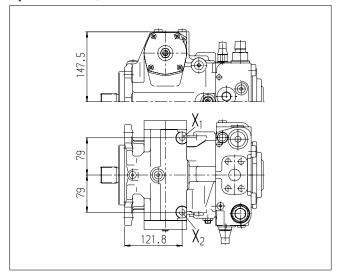
Proportional control hydraulic, pilot-pressure related



**EP** Proportional control electric



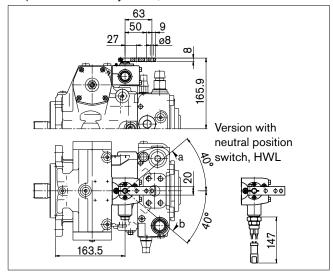
**DG**Hydraulic control, direct controlled



Before finalizing your design, request a binding installation drawing. Dimensions in mm.

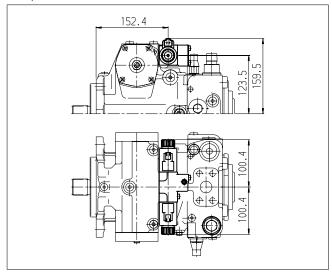
### HW

Proportional control hydraulic, mechanical servo



ΕZ

Two-point control electric

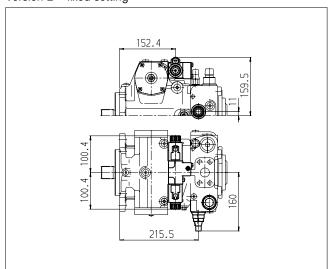


Before finalizing your design, request a binding installation drawing. Dimensions in mm.

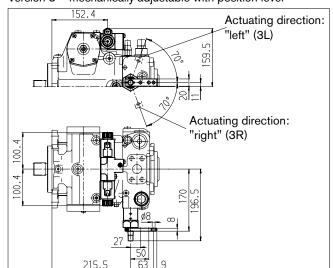
# Dimensions size 71

### DA - control valve

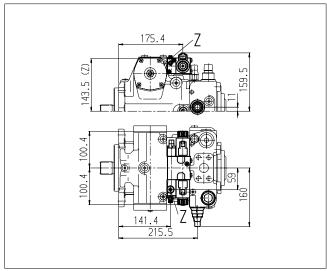
Version 2 - fixed setting



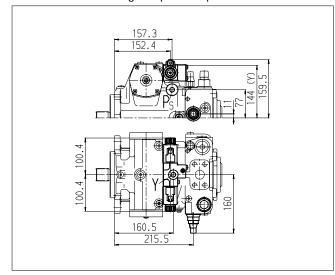
Version 3 - mechanically adjustable with position lever



Version 4/8 - fixed setting and inch valve mounted



Version 7 - fixed setting and ports for pilot control device

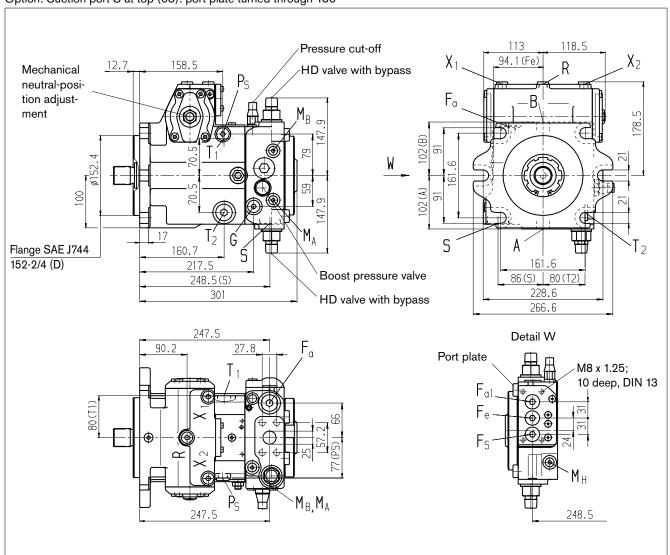


Before finalizing your design, request a binding installation drawing. Dimensions in mm.

### NV - Version without control module

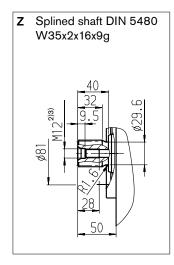
Standard: Suction port S at bottom (02)

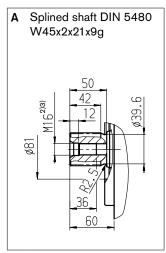
Option: Suction port S at top (03): port plate turned through 180°

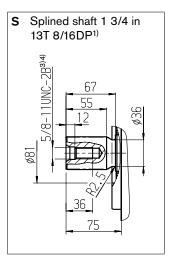


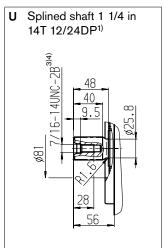
# Before finalizing your design, request a binding installation drawing. Dimensions in mm.

#### **Drive shafts**









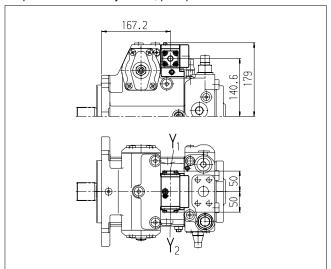
#### **Ports**

Designation	Port for	Standard	Size <sup>3)</sup>	Maximum pressure [bar] <sup>5)</sup>	State <sup>11)</sup>
A, B	Service line Fastening thread A/B	SAE J518 <sup>6)</sup> DIN 13	1 in M12 x 1.75; 17 deep	450	0
S	Suction line	DIN 38529)	M42 x 2; 20 deep	5	O <sup>7)</sup>
T <sub>1</sub>	Drain line	DIN 3852 <sup>9)</sup>	M26 x 1.5; 16 deep	3	O <sub>8)</sub>
T <sub>2</sub>	Drain line	DIN 38529)	M26 x 1.5; 16 deep	3	X <sub>8)</sub>
R	Air bleed	DIN 38529)	M16 x 1.5; 12 deep	3	Χ
X <sub>1</sub> , X <sub>2</sub>	Control pressure (upstream of orifice)	DIN 38529)	M16 x 1.5; 12 deep	40	Χ
X <sub>1</sub> , X <sub>2</sub>	Control pressure (upstream of orifice, DG only)	DIN 3852 <sup>9)</sup>	M16 x 1.5; 12 deep	40	0
X <sub>3,</sub> X <sub>4</sub> <sup>10)</sup>	Stroking chamber pressure	DIN 3852 <sup>9)</sup>	M12 x 1.5; 12 deep	40	Χ
G	Boost pressure	DIN 38529)	M18 x 1.5; 12 deep	40	Χ
Ps	Pilot pressure	DIN 38529)	M18 x 1.5; 12 deep	40	Χ
Ps	Pilot pressure (DA7 only)	DIN 3852 <sup>9)</sup>	M18 x 1.5; 12 deep	40	0
Υ	Pilot pressure (DA7 only)	DIN 38529)	M18 x 1.5; 12 deep	40	0
M <sub>A</sub> , M <sub>B</sub>	Measuring pressure A, B	DIN 38529)	M12 x 1.5; 12 deep	450	Χ
M <sub>H</sub>	Measuring high pressure	DIN 38529)	M12 x 1.5; 12 deep	450	Χ
F <sub>a</sub>	Boost pressure inlet	DIN 3852 <sup>9)</sup>	M26 x 1.5; 16 deep	40	Χ
F <sub>a1</sub>	Boost pressure, inlet (mountable filter)	DIN 3852 <sup>9)</sup>	M22 x 1.5; 14 deep	40	Χ
F <sub>e</sub>	Boost pressure outlet	DIN 3852 <sup>9)</sup>	M22 x 1.5; 14 deep	40	X
F <sub>S</sub>	Line from filter to suction line (cold start)	DIN 3852 <sup>9)</sup>	M22 x 1.5; 14 deep	40	Х
Y <sub>1</sub> , Y <sub>2</sub>	Pilot signal (HD only)	DIN 3852 <sup>9)</sup>	M14 x 1.5; 12 deep	40	0
Z	Inch signal (DA4 and 8 only)	DIN 3852 <sup>9)</sup>	M10 x 1; 8 deep	40	Χ

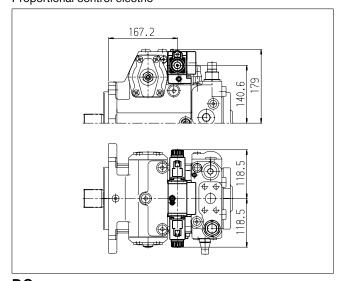
- 1) ANSI B92.1a, 30° pressure angle, flat root, side fit, tolerance class 5
- 2) Center bore according to DIN 332 (thread according to DIN 13)
- 3) Observe the general instructions on page 68 for the maximum tightening torques.
- 4) Thread according to ASME B1.1
- 5) Momentary pressure spikes may occur depending on the application. Keep this in mind when selecting measuring devices and fittings.
- 6) Only dimensions according to SAE J518, metric fastening thread is a deviation from standard.
- 7) Plugged with external supply.
- 8) Depending on installation position, T<sub>1</sub> or T<sub>2</sub> must be connected (see also installation instructions on pages 65 and 66).
- 9) The spot face can be deeper than specified in the appropriate standard.
- 10) Optional, see page 56
- 11) O = Must be connected (plugged on delivery)
  - X = Plugged (in normal operation)

HD

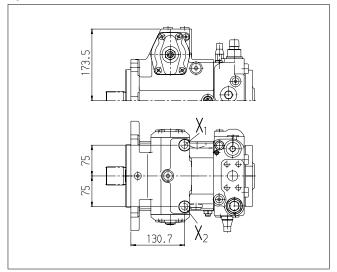
Proportional control hydraulic, pilot-pressure related



**EP** Proportional control electric



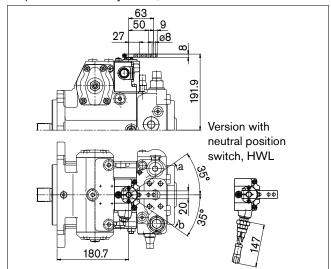
**DG**Hydraulic control, direct controlled



Before finalizing your design, request a binding installation drawing. Dimensions in mm.

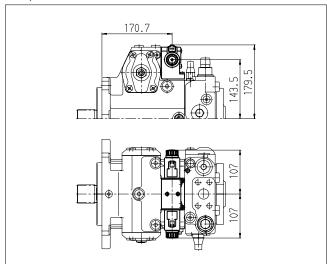
### HW

Proportional control hydraulic, mechanical servo



ΕZ

Two-point control electric

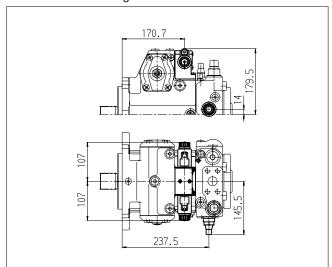


Before finalizing your design, request a binding installation drawing. Dimensions in mm.

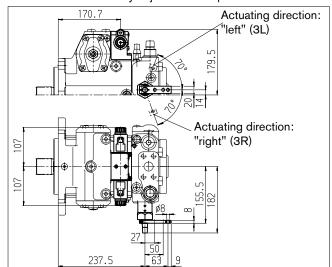
# Dimensions size 90

# DA - control valve

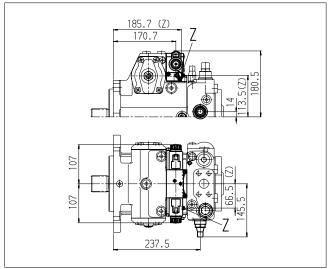
Version 2 - fixed setting



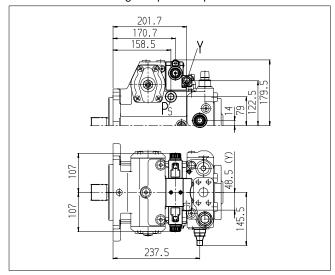
Version 3 - mechanically adjustable with position lever



Version 4/8 - fixed setting and inch valve mounted



Version 7 - fixed setting and ports for pilot control device

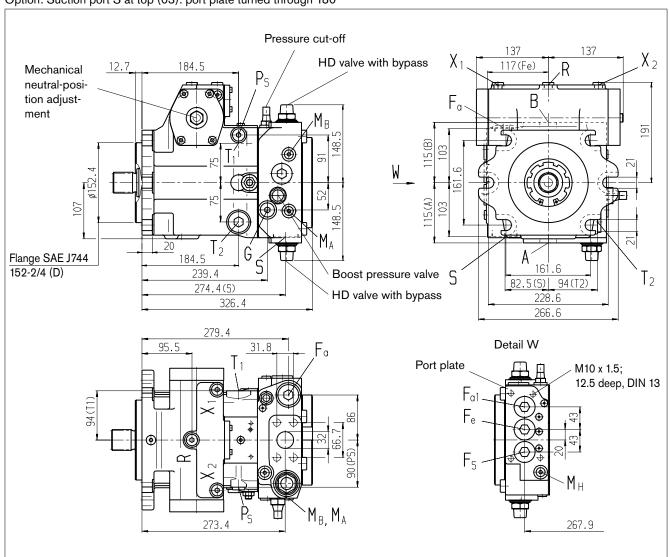


Before finalizing your design, request a binding installation drawing. Dimensions in mm.

# NV - Version without control module

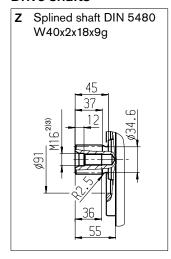
Standard: Suction port S at bottom (02)

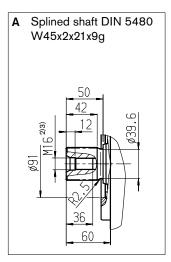
Option: Suction port S at top (03): port plate turned through 180°

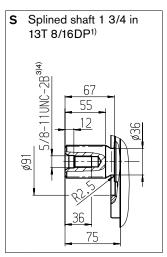


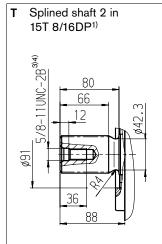
Before finalizing your design, request a binding installation drawing. Dimensions in mm.

### **Drive shafts**









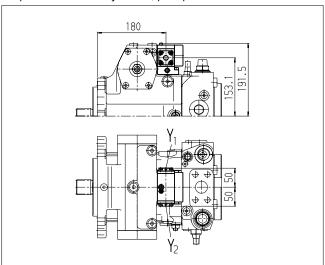
#### **Ports**

Designation	Port for	Standard	Size <sup>3)</sup>	Maximum pressure [bar] <sup>5)</sup>	State <sup>11)</sup>
A, B	Service line Fastening thread A/B	SAE J518 <sup>6)</sup> DIN 13	1 1/4 in M14 x 2; 19 deep	450	0
S	Suction line	DIN 3852 <sup>9)</sup>	M48 x 2; 22 deep	5	O <sup>7)</sup>
T <sub>1</sub>	Drain line	DIN 3852 <sup>9)</sup>	M33 x 2; 18 deep	3	O <sub>8)</sub>
T <sub>2</sub>	Drain line	DIN 3852 <sup>9)</sup>	M33 x 2; 18 deep	3	X <sub>8)</sub>
R	Air bleed	DIN 3852 <sup>9)</sup>	M16 x 1.5; 12 deep	3	Χ
X <sub>1</sub> , X <sub>2</sub>	Control pressure (upstream of orifice)	DIN 3852 <sup>9)</sup>	M16 x 1.5; 12 deep	40	Х
X <sub>1</sub> , X <sub>2</sub>	Control pressure (upstream of orifice, DG only)	DIN 3852 <sup>9)</sup>	M16 x 1.5; 12 deep	40	0
X <sub>3,</sub> X <sub>4</sub> <sup>10)</sup>	Stroking chamber pressure	DIN 3852 <sup>9)</sup>	M12 x 1.5; 12 deep	40	Χ
G	Boost pressure	DIN 3852 <sup>9)</sup>	M22 x 1.5; 14 deep	40	Χ
G P <sub>S</sub>	Pilot pressure	DIN 3852 <sup>9)</sup>	M18 x 1.5; 12 deep	40	Χ
P <sub>S</sub> Y	Pilot pressure (DA7 only)	DIN 3852 <sup>9)</sup>	M18 x 1.5; 12 deep	40	0
Υ	Pilot pressure (DA7 only)	DIN 3852 <sup>9)</sup>	M18 x 1.5; 12 deep	40	0
M <sub>A</sub> , M <sub>B</sub>	Measuring pressure A, B	DIN 3852 <sup>9)</sup>	M12 x 1.5; 12 deep	450	Χ
M <sub>H</sub>	Measuring high pressure	DIN 3852 <sup>9)</sup>	M12 x 1.5; 12 deep	450	Χ
Fa	Boost pressure inlet	DIN 3852 <sup>9)</sup>	M33 x 2; 18 deep	40	Χ
F <sub>a1</sub>	Boost pressure, inlet (mountable filter)	DIN 3852 <sup>9)</sup>	M33 x 2; 18 deep	40	Х
F <sub>e</sub>	Boost pressure outlet	DIN 3852 <sup>9)</sup>	M33 x 2; 18 deep	40	Χ
F <sub>S</sub>	Line from filter to suction line (cold start)	DIN 3852 <sup>9)</sup>	M33 x 2; 18 deep	40	Х
Y <sub>1</sub> , Y <sub>2</sub>	Pilot signal (HD only)	DIN 3852 <sup>9)</sup>	M14 x 1.5; 12 deep	40	0
Z	Inch signal (DA4 and 8 only)	DIN 3852 <sup>9)</sup>	M10 x 1; 8 deep	40	Χ

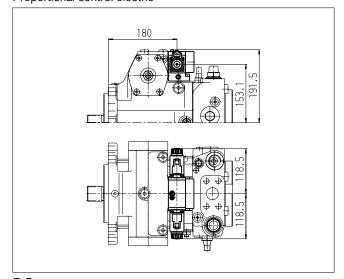
- 1) ANSI B92.1a, 30° pressure angle, flat root, side fit, tolerance class 5
- 2) Center bore according to DIN 332 (thread according to DIN 13)
- 3) Observe the general instructions on page 68 for the maximum tightening torques.
- 4) Thread according to ASME B1.1
- 5) Momentary pressure spikes may occur depending on the application. Keep this in mind when selecting measuring devices and fittings.
- 6) Only dimensions according to SAE J518, metric fastening thread is a deviation from standard.
- 7) Plugged with external supply.
- 8) Depending on installation position, T<sub>1</sub> or T<sub>2</sub> must be connected (see also installation instructions on pages 65 and 66).
- 9) The spot face can be deeper than specified in the appropriate standard.
- 10) Optional, see page 56
- 11) O = Must be connected (plugged on delivery)
  - X = Plugged (in normal operation)

HD

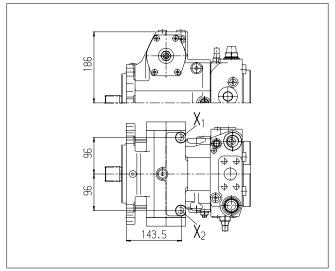
Proportional control hydraulic, pilot-pressure related



**EP** Proportional control electric



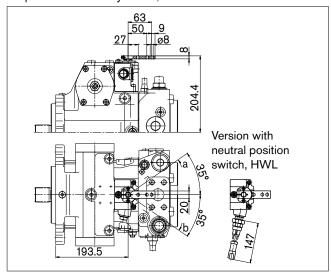
**DG** Hydraulic control, direct controlled



Before finalizing your design, request a binding installation drawing. Dimensions in mm.

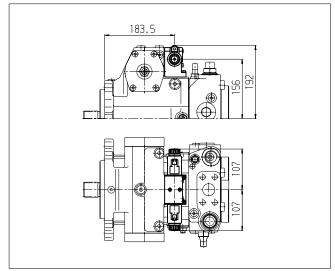
# HW

Proportional control hydraulic, mechanical servo



ΕZ

Two-point control electric

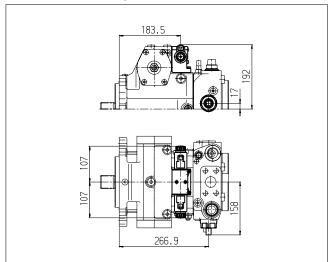


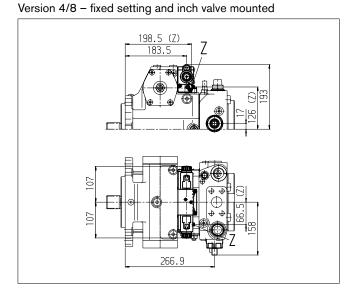
Before finalizing your design, request a binding installation drawing. Dimensions in mm.

# Dimensions size 125

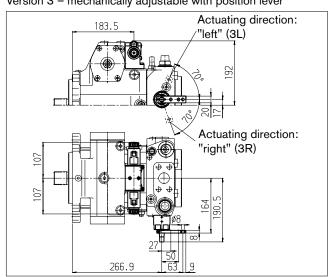
# DA - control valve

Version 2 - fixed setting

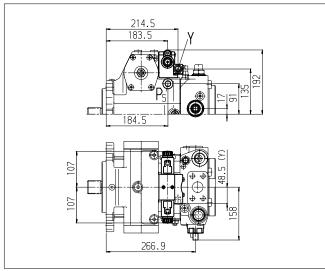




Version 3 – mechanically adjustable with position lever



Version 7 - fixed setting and ports for pilot control device

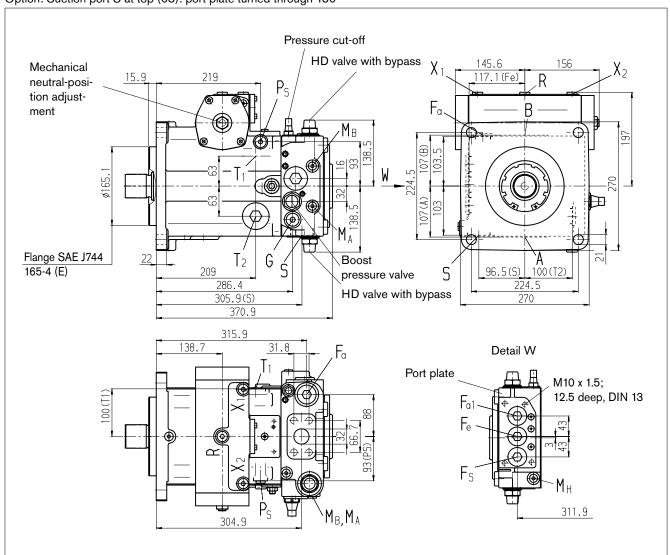


Before finalizing your design, request a binding installation drawing. Dimensions in mm.

# NV - Version without control module

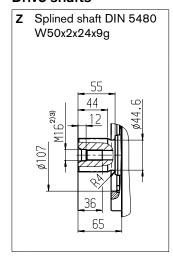
Standard: Suction port S at bottom (02)

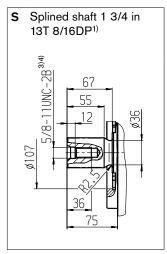
Option: Suction port S at top (03): port plate turned through 180°

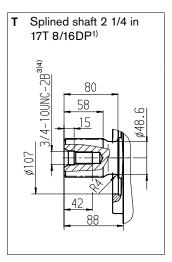


# Before finalizing your design, request a binding installation drawing. Dimensions in mm.

### **Drive shafts**







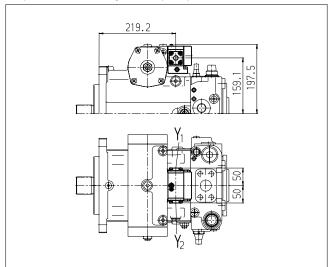
#### **Ports**

Designation	Port for	Standard	Size <sup>3)</sup>	Maximum pressure [bar] <sup>5)</sup>	State <sup>11)</sup>
A, B	Service line Fastening thread A/B	SAE J518 <sup>6)</sup> DIN 13	1 1/4 in M14 x 2; 19 deep	450	Ο
S	Suction line	DIN 3852 <sup>9)</sup>	M48 x 2; 22 deep	5	O <sup>7)</sup>
T <sub>1</sub>	Drain line	DIN 3852 <sup>9)</sup>	M42 x 2; 20 deep	3	O <sub>8)</sub>
T <sub>2</sub>	Drain line	DIN 3852 <sup>9)</sup>	M42 x 2; 20 deep	3	X <sup>8)</sup>
R	Air bleed	DIN 3852 <sup>9)</sup>	M16 x 1.5; 12 deep	3	Χ
X <sub>1</sub> , X <sub>2</sub>	Control pressure (upstream of orifice)	DIN 3852 <sup>9)</sup>	M16 x 1.5; 12 deep	40	Χ
X <sub>1</sub> , X <sub>2</sub>	Control pressure (upstream of orifice, DG only)	DIN 3852 <sup>9)</sup>	M16 x 1.5; 12 deep	40	0
X <sub>3,</sub> X <sub>4</sub> <sup>10)</sup>	Stroking chamber pressure	DIN 3852 <sup>9)</sup>	M12 x 1.5; 12 deep	40	Х
G	Boost pressure	DIN 3852 <sup>9)</sup>	M22 x 1.5; 14 deep	40	Χ
G P <sub>S</sub>	Pilot pressure	DIN 3852 <sup>9)</sup>	M18 x 1.5; 12 deep	40	Χ
Ps	Pilot pressure (DA7 only)	DIN 38529)	M18 x 1.5; 12 deep	40	0
Υ	Pilot pressure (DA7 only)	DIN 3852 <sup>9)</sup>	M18 x 1.5; 12 deep	40	0
M <sub>A</sub> , M <sub>B</sub>	Measuring pressure A, B	DIN 38529)	M12 x 1.5; 12 deep	450	Χ
M <sub>H</sub>	Measuring high pressure	DIN 3852 <sup>9)</sup>	M12 x 1.5; 12 deep	450	Χ
Fa	Boost pressure inlet	DIN 3852 <sup>9)</sup>	M33 x 2; 18 deep	40	Х
F <sub>a1</sub>	Boost pressure, inlet (mountable filter)	DIN 3852 <sup>9)</sup>	M33 x 2; 18 deep	40	Х
F <sub>e</sub>	Boost pressure outlet	DIN 3852 <sup>9)</sup>	M33 x 2; 18 deep	40	Χ
F <sub>S</sub>	Line from filter to suction line (cold start)	DIN 3852 <sup>9)</sup>	M33 x 2; 18 deep	40	Х
Y <sub>1</sub> , Y <sub>2</sub>	Pilot signal (HD only)	DIN 3852 <sup>9)</sup>	M14 x 1.5; 12 deep	40	0
Z	Inch signal (DA4 and 8 only)	DIN 3852 <sup>9)</sup>	M10 x 1; 8 deep	40	Χ

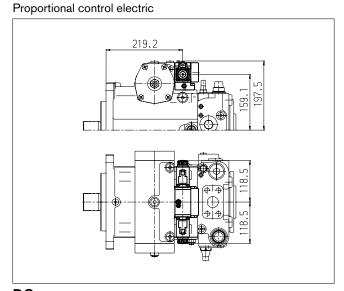
- 1) ANSI B92.1a, 30° pressure angle, flat root, side fit, tolerance class 5
- 2) Center bore according to DIN 332 (thread according to DIN 13)
- 3) Observe the general instructions on page 68 for the maximum tightening torques.
- 4) Thread according to ASME B1.1
- 5) Momentary pressure spikes may occur depending on the application. Keep this in mind when selecting measuring devices and fittings.
- 6) Only dimensions according to SAE J518, metric fastening thread is a deviation from standard.
- 7) Plugged with external supply.
- 8) Depending on installation position, T<sub>1</sub> or T<sub>2</sub> must be connected (see also installation instructions on pages 65 and 66).
- 9) The spot face can be deeper than specified in the appropriate standard.
- 10) Optional, see page 56
- 11) O = Must be connected (plugged on delivery)
  - X = Plugged (in normal operation)

HD

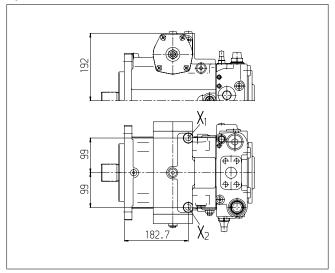
Proportional control hydraulic, pilot-pressure related



**EP** 



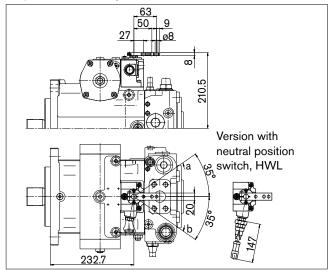
**DG**Hydraulic control, direct controlled



Before finalizing your design, request a binding installation drawing. Dimensions in mm.

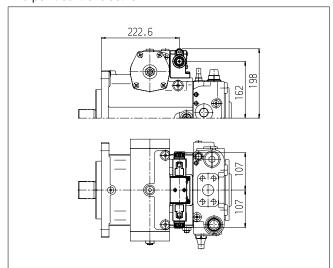
# HW

Proportional control hydraulic, mechanical servo



ΕZ

Two-point control electric

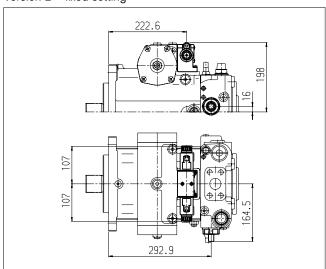


Before finalizing your design, request a binding installation drawing. Dimensions in mm.

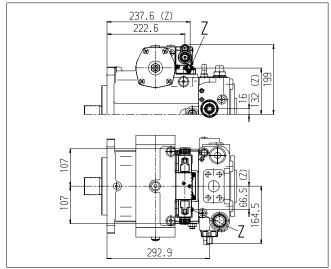
# Dimensions size 180

# DA - control valve

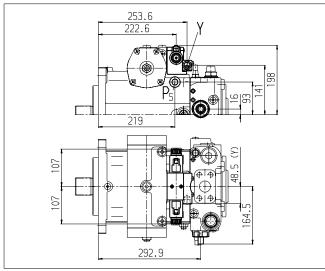
Version 2 - fixed setting



Version 4/8 - fixed setting and inch valve mounted



Version 7 - fixed setting and ports for pilot control device

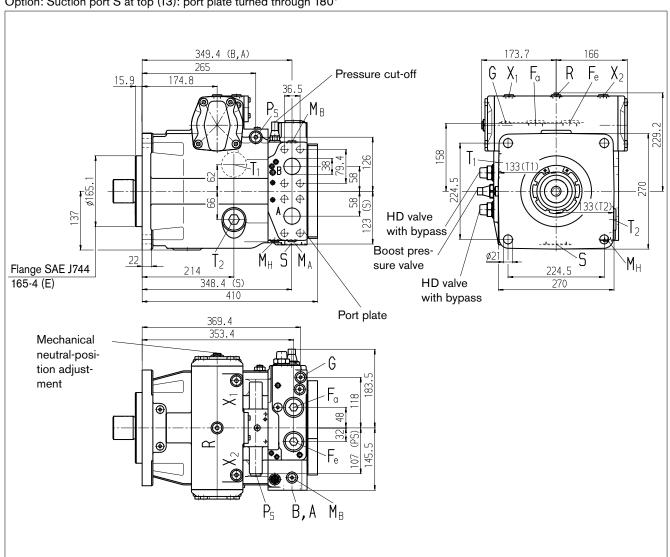


Before finalizing your design, request a binding installation drawing. Dimensions in mm.

# NV - Version without control module

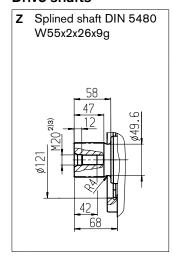
Standard: Suction port S at bottom (10)

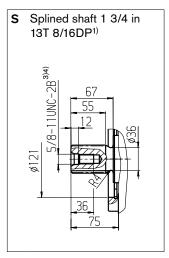
Option: Suction port S at top (13): port plate turned through 180°

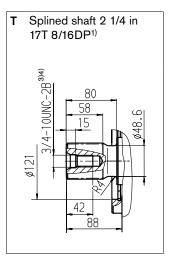


# Before finalizing your design, request a binding installation drawing. Dimensions in mm.

### **Drive shafts**







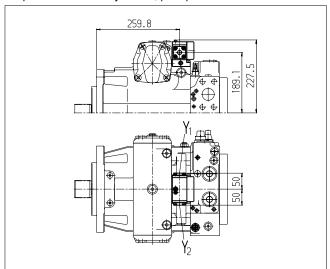
#### **Ports**

Ports					
Designation	Port for	Standard	Size <sup>3)</sup>	Maximum pressure [bar] <sup>5)</sup>	State <sup>11)</sup>
A, B	Service line Fastening thread A/B	SAE J518 <sup>6)</sup> DIN 13	1 1/2 in M16 x 2; 21 deep	450	Ο
S	Suction line	DIN 3852 <sup>9)</sup>	M48 x 2; 22 deep	5	O <sup>7)</sup>
T <sub>1</sub>	Drain line	DIN 3852 <sup>9)</sup>	M42 x 2; 20 deep	3	O <sub>8</sub> )
T <sub>2</sub>	Drain line	DIN 3852 <sup>9)</sup>	M42 x 2; 20 deep	3	X <sub>8)</sub>
R	Air bleed	DIN 3852 <sup>9)</sup>	M16 x 1.5; 12 deep	3	Х
X <sub>1</sub> , X <sub>2</sub>	Control pressure (upstream of orifice)	DIN 3852 <sup>9)</sup>	M16 x 1.5; 12 deep	40	Х
X <sub>1</sub> , X <sub>2</sub>	Control pressure (upstream of orifice, DG only)	DIN 3852 <sup>9)</sup>	M16 x 1.5; 12 deep	40	0
X <sub>3</sub> , X <sub>4</sub> <sup>10)</sup>	Stroking chamber pressure	DIN 3852 <sup>9)</sup>	M16 x 1.5; 12 deep	40	Х
G	Boost pressure	DIN 3852 <sup>9)</sup>	M14 x 1.5; 12 deep	40	Х
Ps	Pilot pressure	DIN 3852 <sup>9)</sup>	M18 x 1.5; 12 deep	40	Х
Ps	Pilot pressure (DA7 only)	DIN 3852 <sup>9)</sup>	M18 x 1.5; 12 deep	40	0
Υ	Pilot pressure (DA7 only)	DIN 3852 <sup>9)</sup>	M18 x 1.5; 12 deep	40	0
M <sub>A</sub> , M <sub>B</sub>	Measuring pressure A, B	DIN 3852 <sup>9)</sup>	M14 x 1.5; 12 deep	450	Χ
M <sub>H</sub>	Measuring high pressure	DIN 3852 <sup>9)</sup>	M14 x 1.5; 12 deep	450	Х
Fa	Boost pressure inlet	DIN 3852 <sup>9)</sup>	M33 x 2; 18 deep	40	X
F <sub>e</sub>	Boost pressure outlet	DIN 3852 <sup>9)</sup>	M33 x 2; 18 deep	40	Х
Y <sub>1</sub> , Y <sub>2</sub>	Pilot signal (HD only)	DIN 3852 <sup>9)</sup>	M14 x 1.5; 12 deep	40	0
Z	Inch signal (DA4 and 8 only)	DIN 3852 <sup>9)</sup>	M10 x 1; 8 deep	40	Χ

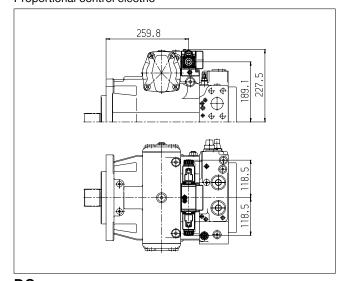
- 1) ANSI B92.1a, 30° pressure angle, flat root, side fit, tolerance class 5
- 2) Center bore according to DIN 332 (thread according to DIN 13)
- 3) Observe the general instructions on page 68 for the maximum tightening torques.
- 4) Thread according to ASME B1.1
- 5) Momentary pressure spikes may occur depending on the application. Keep this in mind when selecting measuring devices and fittings.
- 6) Only dimensions according to SAE J518, metric fastening thread is a deviation from standard.
- 7) Plugged with external supply.
- 8) Depending on installation position, T<sub>1</sub> or T<sub>2</sub> must be connected (see also installation instructions on pages 65 and 66).
- 9) The spot face can be deeper than specified in the appropriate standard.
- 10) Optional, see page 56
- 11) O = Must be connected (plugged on delivery)
  - X = Plugged (in normal operation)

HD

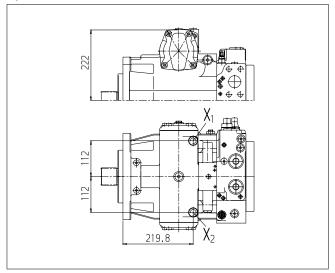
Proportional control hydraulic, pilot-pressure related



**EP**Proportional control electric



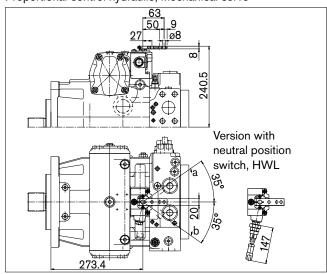
**DG**Hydraulic control, direct controlled



Before finalizing your design, request a binding installation drawing. Dimensions in mm.

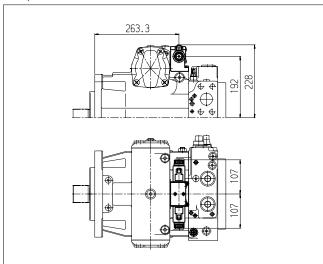
# HW

Proportional control hydraulic, mechanical servo



### ΕZ

Two-point control electric

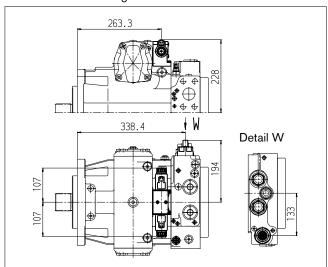


Before finalizing your design, request a binding installation drawing. Dimensions in mm.

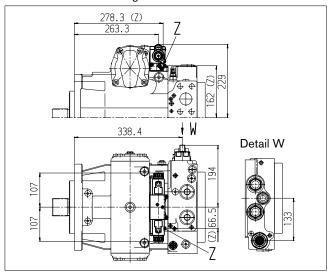
# Dimensions size 250

# DA - control valve

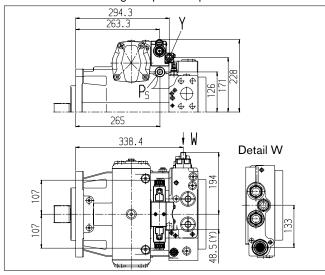
Version 2 - fixed setting



Version 4/8 - fixed setting and inch valve mounted



Version 7 - fixed setting and ports for pilot control device

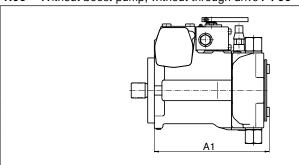


# Through drive dimensions

Before finalizing your design, request a binding installation drawing. Dimensions in mm.

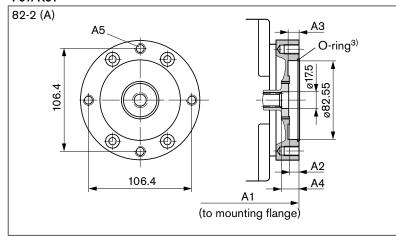
Flange SAE J744 Coupling for splined shaft (according to ANSI B92.1a) <sup>1)</sup>			28	40	56	71	90	125	180	250	
82-2 (A)	5/8 in	9T 16/32DP	•	•	•	•	•	•	•	•	.01
101-2 (B)	7/8 in	13T 16/32DP	•	•	•	•	•	•	•	•	.02
	1 in	15T 16/32DP	•	•	•	•	•	•	•	•	.04

N00 - Without boost pump, without through drive / F00 - With boost pump, without through drive



NG	A1 (N00)	A1 (F00)
28	213.9	223.4
40	220.2	235.7
56	239.4	256.4
71	279.1	293.6
90	287	301
125	320.9	326.4
180	370.9	370.9
250	398.2	409

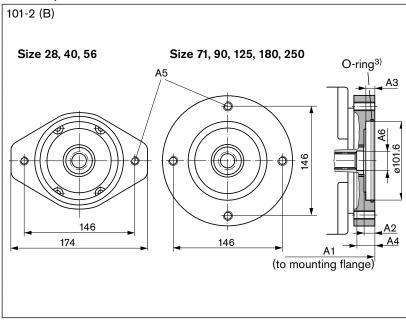
### F01/K014)



NG	A1 (F01)	A1 (K01)	A2	А3	<b>A</b> 4
28	227.9	227.9	7.5	7.5	14.5
40	239.7	234.2	9	9	18
56	261.4	254.9	10	10	18
71	297.6	297.6	9	10	17
90	304	304	9	8	-
125	330.9	330.9	10.5	9	-
180	378.4	378.4	7.5	7.5	15.5
250	426.9	426.2	11	11	18

NG	A5 <sup>2)</sup>
28 to 125	M10 x 1.5; 15 deep
180, 250	M10 x 1.5; 16.5 deep

### F02/K02; F04/K044)



NG	A1	A2	А3	A4 (02	2) A4 (04)
28	230.4	9.7	9.7	16.2	13.7
40	240.7	11	11 <sup>5)</sup>	17	16
56	262.4	12	11	19.5	18.5
71	300.6	13	9.8	17	15.5
90	305	9	11	17	15
125	330.9	10	11	17	16.5
180	381.4	11	11	19	18
250	428.9	11	11	16	15.5

NG	A5 <sup>2)</sup>
28 to 56	M12 x 1.75; 19 deep
71, 90, 180, 250	M12 x 1.75; 21 deep
125	M12 x 1.75; 18 deep

	A6
F02 / K02	ø 24
F04 / K04	ø 27

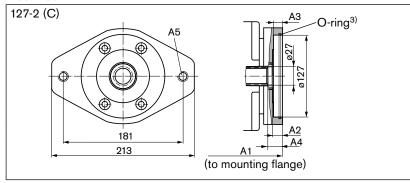
- 1) 30° pressure angle, flat root, side fit, tolerance class 5
- 2) Thread according to DIN 13, observe the general instructions on page 68 for the maximum tightening torques.
- 3) O-ring included in the delivery contents
- 4) The illustration shows the 2-hole version. Please state in plain text whether the 2-hole horizontal or the 2-hole vertical version is used.
- 5) For F04/K04 9.7 mm

# Through drive dimensions

Before finalizing your design, request a binding installation drawing. Dimensions in mm.

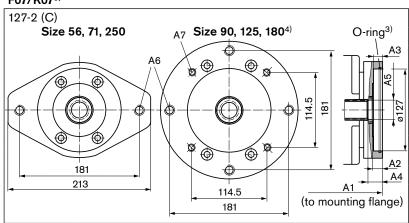
Flange SAE J744	nge SAE J744 Coupling for splined shaft (according to ANSI B92.1a)1)			40	56	71	90	125	180	250	
127-2 (C)	1 in	15T 16/32DP	-	•	-	-	-	-	-	-	.09
	1 1/4 in	14T 12/24DP	-	_	•	•	•	•	•	•	.07
152-2/4 (D)	W35	2x16x9g (according to DIN 5480)	-	_	-	-	•	-	-	_	.73
	1 3/4 in	13T 8/16DP	-	_	-	_	_	•	•	•	.69

#### F09/K09



NG	A1	A2	А3	<b>A</b> 4	
40	244.7	14	14	19.5	
NG	A5 <sup>2)</sup>				
40	M16 x	2: 20 d	deep		

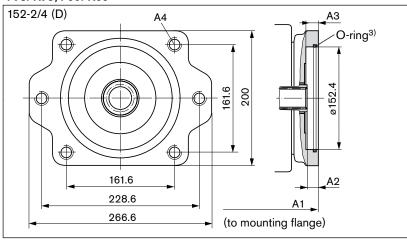
### F07/K07<sup>5)</sup>



NG	<b>A</b> 1	A2	А3	<b>A</b> 4	A5
56	266.4	15	14	17.5	ø32.7
71	303.6	15	13.5	20	
90	309	13	14	20.5	
125	335.9	15	15.5	22.5	ø33.5
180	384.4	14	19	17	
250	425.9	16	14	16	

NG	A6 <sup>2)</sup>	A7 <sup>2)</sup>
56	M16 x 2; 20 deep	_
71, 250	M16 x 2; 24 deep	_
90, 125, 180	M16 x 2; 23 deep	M12 x 1.75; 18 deep

### F73/K73; F69/K69<sup>6)</sup>



90 309 12 14 125 343.9 18 14 M20 x 2.5; 180 391.9 20.9 18 20 deep	NG	A1	A2	А3	A4 <sup>2)</sup>
180 391.9 20.9 18 20 deep	90	309	12	14	_
	125	343.9	18	14	M20 x 2.5;
250 444 9 9 17	180	391.9	20.9	18	20 deep
200   444.0 0 1/	250	444.9	9	17	_

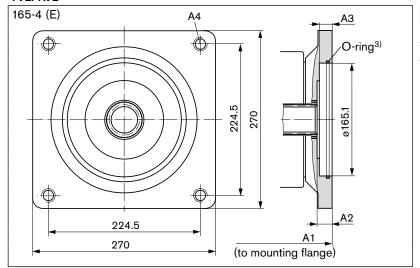
- 1) 30° pressure angle, flat root, side fit, tolerance class 5
- 2) Thread according to DIN 13, observe the general instructions on page 68 for the maximum tightening torques.
- 3) O-ring included in the delivery contents
- 4) Size 180 only with SAE 2-hole flange
- 5) The illustration shows the 4- and the 2-hole version. Please state in plain text whether the 4-hole, the 2-hole horizontal or the 2-hole vertical version is used.
- 6) The illustration shows the 4+2-hole version. Please state in plain text whether the 2-hole, the 4-hole or the 4+2-hole version is used.

# Through drive dimensions

Before finalizing your design, request a binding installation drawing. Dimensions in mm.

Flange SAE J744	Coupling for splined shaft (according to ANSI B92.1a)1)	28	40	56	71	90	125	180	250		_
165-4 (E)	1 3/4 in 13T 8/16DP	_	_	_	_	_	_	•	•	.72	l

### F72/K72



NG	A1	A2	А3	A4 <sup>2)</sup>
180	391.9	20.9	18	M20 x 2.5;
250	444.9	9	17	20 deep

- 1) 30° pressure angle, flat root, side fit, tolerance class 5
- 2) Thread according to DIN 13, observe the general instructions on page 68 for the maximum tightening torques.
- 3) O-ring included in the delivery contents

# Overview of mounting options

Through d	rive <sup>1)</sup>		Mounting options – 2nd pump							
Flange	Coupling for splined shaft	Short code	A4VG/32 NG (shaft)	A10V(S)O/31 Size (shaft)	A10V(S)O/53 Size (shaft)	A4FO NG (shaft)	A11VO/1 NG (shaft)	A10VG NG (shaft)	External gear pump <sup>2)</sup>	
82-2 (A)	5/8 in	F/K01	_	18 (U)	10 (U)	_	-	_	Series F Size 4 to 22	
101-2 (B)	7/8 in	F/K02	_	28 (S, R) 45 (U, W)	28 (S, R) 45 (U, W)	16 (S) 22 (S) 28 (S)	_	18 (S)	Series N Size 20 to 36 Series G Size 32 to 50	
	1 in	F/K04	28 (S)	45 (S, R)	45 (S, R) 60 (U, W)	_	40 (S)	28 (S) 45 (S)	_	
127-2 (C)	1 in	F/K09	40 (U)	71 (U, W)	60 (U, W)	_	_	_	_	
	1 1/4 in	F/K07	40 (S) 56 (S) 71 (S)	71 (S, R) 100 (U, W)	85 (U, W)	_	60 (S)	63 (S)	_	
152-2/4 (D)	W35	F/K73	90 (Z)	_	_	_	-	_	_	
	1 3/4 in	F/K69	90 (S) 125 (S)	140 (S)	-	_	95 (S) 130 (S) 145 (S)	_	-	
165-4 (E)	1 3/4 in	F/K72	180 (S) 250 (S)	=	-	_	190 (S) 260 (S)	_	_	

<sup>1)</sup> Availability of the individual sizes, see ordering code on page 3.

<sup>2)</sup> Bosch Rexroth recommends special versions of the gear pumps. Please contact us.

# Combination pumps A4VG + A4VG

Before finalizing your design, request a binding installation drawing. Dimensions in mm.

### Total length A

A4VG	A4VG (2nd pump) <sup>3)</sup>								
(1st pump)	NG28	NG40	NG56	NG71	NG90	NG125	NG180	NG250	
NG28	453.8	=	-	=	=	=	_	_	
NG40	464.1	480.4	<u>-</u>	=	=	=	-	_	
NG56	485.8	502.1	522.8	=	_	_	_	_	
NG71	524.0	539.3	560.0	597.2	_	=	-	_	
NG90	528.4	544.7	565.4	602.6	610.0	-	=	_	
NG125	554.3	571.6	592.3	629.5	644.9	670.3	_	_	
NG180	604.8	620.1	640.8	678.0	692.9	718.3	762.8	_	
NG250	652.3	661.6	682.3	719.5	745.9	771.3	815.8	854.8	

<sup>1) 2</sup>nd pump without through drive and with boost pump, F00

By using combination pumps, it is possible to have independent circuits without the need for splitter gearboxes.

When ordering combination pumps, the type designations of the 1st and 2nd pumps must be linked by a "+".

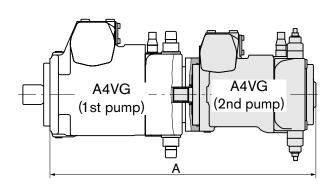
### Ordering example:

# A4VG56EP3D1/32R-NAC02F073SP + A4VG56EP3D1/32R-NSC02F003SP

A tandem pump consisting of two equal sizes is permissible without additional supports assuming that the dynamic acceleration does not exceed maximum 10 g (= 98.1 m/s<sup>2</sup>).

We recommend the use of the 4-hole mounting flanges for size 71 and larger.

For combination pumps consisting of more than two pumps, the mounting flange must be rated for the permissible mass torque.



# High-pressure relief valves

The two high-pressure relief valves protect the hydrostatic transmission (pump and motor) from overload. They limit the maximum pressure in the respective high-pressure line and serve simultaneously as boost valves.

High-pressure relief valves are not working valves and are only suitable for pressure spikes or high rates of pressure change.

#### Setting ranges

High-pressure relief valve, direct controlled (size 28 to 56)	Differential pressure setting Δp <sub>HD</sub>
Setting range for valve 3, 5	420 bar
Δp 250 - 420 bar	400 bar <sup>1)</sup>
(see ordering code)	360 bar
	340 bar
	320 bar
	300 bar
	270 bar
	250 bar
Setting range for valve 4, 6	250 bar
Δp 100 - 250 bar	230 bar <sup>1)</sup>
(see ordering code)	200 bar
	150 bar
	100 bar

High-pressure relief valve, pilot operated (size 71 to 250)	Differential pressure setting ∆p <sub>HD</sub>
Setting range for valve 1,	420 bar
Δp 100 - 420 bar	400 bar <sup>1)</sup>
(see ordering code)	360 bar
	340 bar
	320 bar
	300 bar
	270 bar
	250 bar
	230 bar
	200 bar
	150 bar
	100 bar

Standard differential pressure setting. If not specified in the order, valves will be set to this value.

### When ordering, state in plain text:

(only the  $\Delta p_{HD}$  values stated in the table are possible)

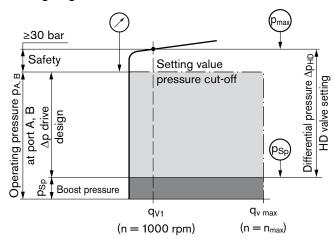
#### High-pressure relief valve A

Differential pressure setting	$\Delta p_{HD} =$ bar
Cracking pressure of the HD valve (at q <sub>V 1</sub> )	_ p <sub>max</sub> = bar
$(p_{max} = \Lambda p_{HD} + p_{Sp})$	

#### High-pressure relief valve B

Differential pressure setting	$\Delta p_{HD} = \dots bar$
Cracking pressure of the HD valve (at $q_{V 1}$ ) ( $p_{max} = \Delta p_{HD} + p_{Sp}$ )	_ p <sub>max</sub> = bar

### Setting diagram



#### Note

The valve settings are made at n=1000 rpm and at  $V_{g\ max}$  ( $q_{v\ 1}$ ). There may be deviations in the cracking pressures with other operating parameters.

#### Example:

Operating Boost pre	400 bar 30 bar			
Differentia	400 bar			
p <sub>A,B</sub> 400 bar	– p <sub>Sp</sub> 30 bar	+ Safety 30 bar	$= \frac{\Delta p_{HD}}{400 \text{ bar}}$	

### Bypass function

A connection between the two high-pressure channels A and B can be established using the bypass valve (e.g. for machine towing).

#### **Towing speed**

The maximum towing speed is dependent on the gear ratio in the vehicle and must be calculated by the vehicle manufacturer. The corresponding flow of Q=30 L/min must not be exceeded.

### Towing distance

The vehicle may only be towed out of the immediate danger zone.

#### Note:

The bypass function and the pilot-controlled high pressure relief valves (size 71 to 250) are not illustrated in the circuit diagrams.

# Pressure cut-off

The pressure cut-off is a pressure control which, after reaching the set pressure, adjusts the displacement of the pump back to  $V_{g\ min}$ .

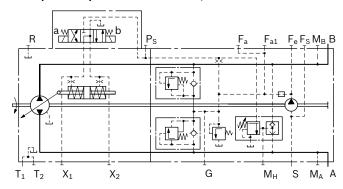
This valve prevents the operation of the high-pressure relief valves when accelerating or decelerating.

The high-pressure relief valves protect against the pressure spikes which occur during fast swiveling of the swashplate and limit the maximum pressure in the system.

The setting range of the pressure cut-off may be anywhere within the entire operating pressure range. However, it must be set 30 bar lower than the setting of the high-pressure relief valves (see setting diagram, page 54).

Please state the setting value of the pressure cut-off in plain text when ordering.

### Schematic with pressure cut-off Example: two-point control electric, EZ1D/EZ2D



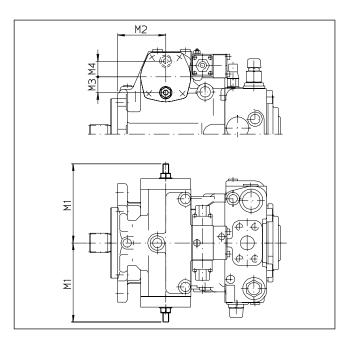
# Mechanical stroke limiter

The mechanical stroke limiter is an auxiliary function allowing the maximum displacement of the pump to be steplessly reduced, regardless of the control module used.

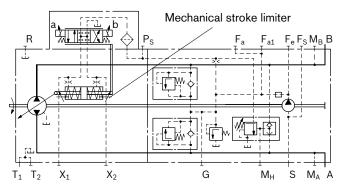
With two threaded pins, the stroke of the stroke piston and thus the maximum swivel angle of the pump is limited.

#### **Dimensions**

NG	M1	M2	М3	M4
28	110.6 max	40.1	24	_
40	110.6 max	38.1	24	_
56	130.5 max	44	25.5	_
71	135.4 max	86.3	_	28.5
90	147 max	95.7	31.5	_
125	162 max	104.5	=	35.5
180	181.6 max	138.7	38	-
250	198.9 max	174.8	39.5	-



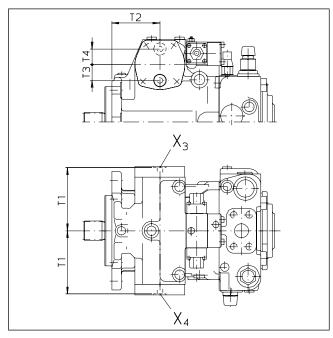
# Schematic1)



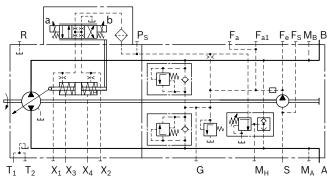
# Ports X<sub>3</sub> and X<sub>4</sub> for stroking chamber pressure

#### **Dimensions**

NG	T1	T2	T3	T4
28	92	40.1	_	24
40	92	38.1	_	24
56	104.5	44	_	25
71	113.5	86.3	28	_
90	111.5	95.7	_	30
125	136	104.5	34	_
180	146.5	138.7	_	35
250	164.5	174.8	_	38



# Schematic1)



Designation	Port for	Standard <sup>2)</sup>	Size <sup>3)</sup>	Maximum pressure [bar]4)	State <sup>5)</sup>
X <sub>3</sub> , X <sub>4</sub>	Stroking chamber pressure	DIN 3852	M12 x 1.5; 12 deep	40	Χ
X <sub>3</sub> , X <sub>4</sub>	Stroking chamber pressure (size 250 only)	DIN 3852	M16 x 1.5; 12 deep	40	Χ

- $_{\mbox{\scriptsize 1)}}$  Sizes 28 and 250 without ports  $F_{a1}$  and  $F_{\mbox{\scriptsize S}}$
- 2) The spot face can be deeper than specified in the appropriate standard.
- 3) Observe the general instructions on page 68 for the maximum tightening torques.
- 4) Momentary pressure spikes may occur depending on the application. Keep this in mind when selecting measuring devices and fittings.
- 5) X = Plugged (in normal operation)

Before finalizing your design, request a binding installation drawing. Dimensions in mm.

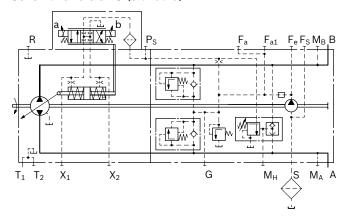
#### Version S (standard)

### Filtration in the suction line of the boost pump

Standard version (preferred)

The filter is not included in the delivery contents.

#### Schematic version S (standard)



### Version E External supply

This variation should be used in versions **without** integrated boost pump (N00 or K..).

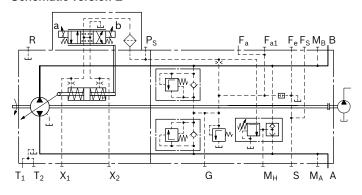
Port S is plugged.

Supply comes from port F<sub>a</sub>.

Filter arrangement \_\_\_\_\_separate

To ensure the functional reliability, maintain the required cleanliness level for the boost fluid fed in at port F<sub>a</sub> (see page 6).

### Schematic version E



#### Version D

# Filtration in the pressure line of the boost pump, ports for external boost circuit filter

Boost pressure inlet \_\_\_\_\_\_ port Fa
Boost pressure outlet \_\_\_\_\_ port Fe
Filter type
Filter with bypass are **not recommended**. For applications with bypass please contact us.

Recommendation \_\_\_\_\_ with contamination indicator

#### Note

For versions with **DG** control (with pilot pressure not from boost circuit), the following filter type should be used:

Filter with bypass and with contamination indicator

Filter arrangement

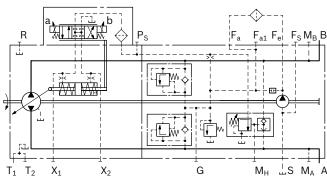
Separate in the pressure line (inline filter)

Permissible differential pressure at filter cartridge At  $\nu=30~\text{mm}^2/\text{s}$  \_\_\_\_\_\_  $\Delta p \leq 1~\text{bar}$  At cold start \_\_\_\_\_\_  $\Delta p \leq 3~\text{bar}$ 

(valid for entire speed range n<sub>min</sub> - n<sub>max</sub>)

The filter is not included in the delivery contents.

#### Schematic version D



Before finalizing your design, request a binding installation drawing. Dimensions in mm.

#### Version K

Filtration in the pressure line of the boost pump, with cold start valve and ports for external boost circuit filter

Version as version D, but with additional cold start valve.

The port plate is equipped with **cold start valve** and thereby protects the system from damage.

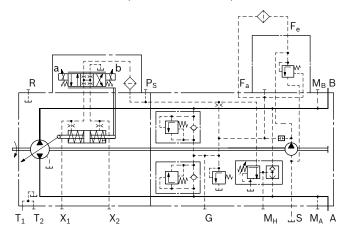
The valve opens at a differential pressure  $\Delta p \ge 6$  bar.

Boost pressure inlet \_\_\_\_\_\_ port  $F_a$ Boost pressure outlet \_\_\_\_\_\_ port  $F_e$ 

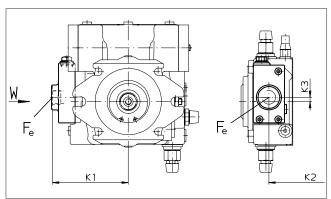
Filter arrangement \_\_\_separate in the pressure line (inline filter)

The filter is not included in the delivery contents.

### Schematic version K (with cold start valve)



#### Dimensions, version K (with cold start valve)



NG	K1	K2	К3	F <sub>e</sub> <sup>1) 2)</sup>
40	122.5	198.7	0	M18 x 1.5; 15 deep
56	125.5	215.4	0	M18 x 1.5; 15 deep
71	145.5	239.0	8	M26 x 1.5; 16 deep
90	139.5	248.5	24	M26 x 1.5; 16 deep
125	172.0	267.9	20	M33 x 2; 18 deep
180	173.0	311.9	3	M33 x 2; 18 deep

- 1) Thread according to DIN 3852, observe the general instructions on page 68 for the maximum tightening torques.
- 2) The spot face can be deeper than specified in the appropriate standard.

# Version F Filtration in the pressure line of the boost pump,

Filter type	filter without bypass
Filtration grade (absolute)	20 microns
Filter material	glass fiber
Pressure rating	100 bar
Filter arrangement	mounted on pump

The filter is equipped with **cold start valve** and thereby protects the system from damage.

The valve opens at a differential pressure  $\Delta p \geq 6$  bar.

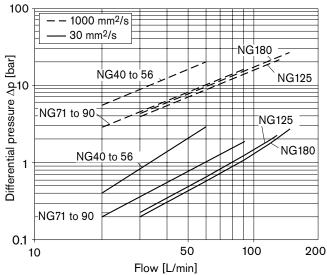
Recommendation

filter mounted

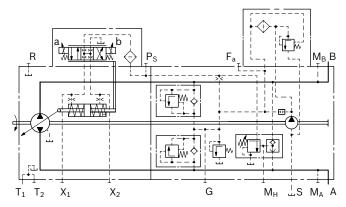
**With** contamination indicator (version P, B) (differential pressure  $\Delta p = 5$  bar)

#### Filter characteristics

Differential pressure/flow characteristics to ISO 3968 (valid for clean filter cartridge).



#### Schematic version F (with filter)



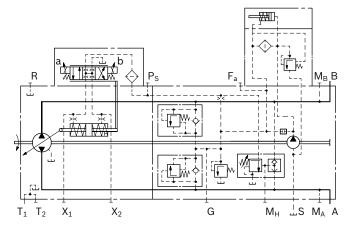
#### Version F

# Filtration in the pressure line of the boost pump, filter mounted, with visual contamination indicator

Version similar to variation F, however additionally with visual contamination indicator.

Indication \_\_\_\_\_ Green/red window Differential pressure (switching pressure) \_\_\_\_  $\Delta p = 5$  bar

### Schematic version P



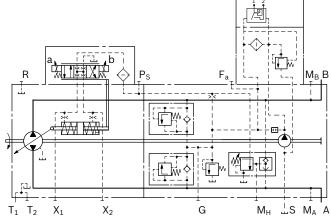
#### ersion B

# Filtration in the pressure line of the boost pump, filter mounted, with electric contamination indicator

Filtration similar to variation F, however additionally with electric contamination indicator.

Indication \_\_\_\_\_\_electric 
Connector design \_\_\_\_\_DEUTSCH DT04-2P-EP04 
(mating connector, see page 62) 
Differential pressure (switching pressure) \_\_\_\_\_  $\Delta p = 5$  bar 
Maximum switching capacity at 
12 V DC \_\_\_\_\_\_ 36 W 
24 V DC \_\_\_\_\_\_ 72 W 
Type of protection: IP 67 \_\_\_\_\_DIN/EN 60529

#### Schematic version B

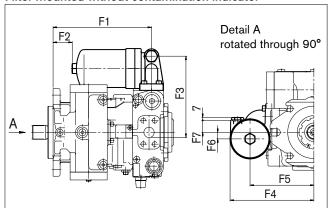


Before finalizing your design, request a binding installation drawing. Dimensions in mm.

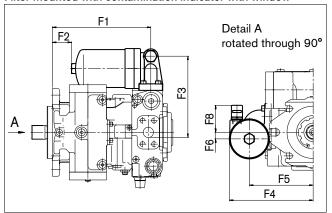
# Dimensions with filter fitted

### **Version F**

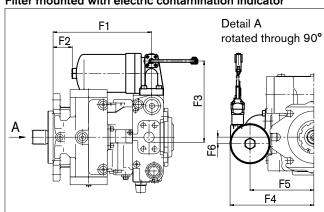
### Filter mounted without contamination indicator



Version P
Filter mounted with contamination indicator with window



Version B Filter mounted with electric contamination indicator



NG	F1	F2	F3	F4	F5	F6	F7	F8
40	201.7	47.7	160	175	135	0	42	78.5
56	218.4	64.4	163	178	138	0	42	78.5
71	239	46.5	185	203.5	155	16	29	65.5
90	248.5	56	179	197.5	149	0	45	81.5
125	235.9	59.4	201	219.5	171	0	53	89.5
180	279.9	40.3	202	220.4	171.9	17	36	72.5

# Swivel angle sensor

For the swivel angle indicator, the pump swivel angle is measured by an electric swivel angle sensor.

As an output parameter, the Hall-effect swivel angle sensor delivers a voltage proportional to the swivel angle (see table of output voltages).

Please contact us if the swivel angle sensor is used for control.

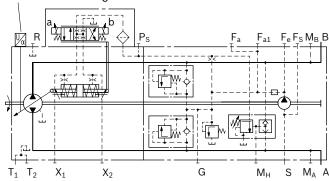
Characteristics			
Supply voltage U <sub>b</sub>	10 to 30	V DC	
Output voltage U <sub>a</sub>	0.5 V (V <sub>g max</sub> )		4.5 V (V <sub>g max</sub> )
Reverse voltage protection	Short cire	cuit-resis	tant
EMC resistance	Details o	n reques	t
Operating temperature range	-40 °C to	+115 °C	;
Vibration resistance sinusoidal vibration EN 60068-2-6	10 <i>g</i> / 5 t	to 2000 l	Нz
Shock resistance continuous shock IEC 68-2-29	25 g		
Resistance to salt spray (DIN 50 021-SS)	96 h		
Type of protection with mounted mating connector	IP67 – D IP69K –		
Housing material	Plastic		

### Output voltage

		Flow direction	Operating pressure	Output vo	ltage at V <sub>g max</sub>
rection of	CW	A to B	$M_{B}$	2.5 V	4.5 V
		B to A	M <sub>A</sub>	2.5 V	0.5 V
Directi rotation	ccw	B to A	M <sub>A</sub>	2.5 V	4.5 V
		A to B	M <sub>B</sub>	2.5 V	0.5 V

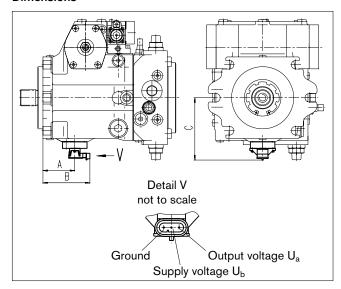
# Schematic

Electric swivel angle sensor



Before finalizing your design, request a binding installation drawing. Dimensions in mm.

#### **Dimensions**



NG	Α	В	С
28	56.6	94	119
40	58.6	96	119
56	60.5	97.5	128.5
71	71.6	108.6	137.5
90	70.7	107.7	145.5
125	78	115	152.5
180	100.7	137.7	153.5
250	105.1	142.1	180.5

### Mating connector

AMP Superseal 1.5; 3-pin

Bosch Rexroth Mat. No. R902602132

Consisting of:	AMP No.
- 1 socket case, 3-pins	282087-1
- 3 single wire seals, yellow	_281934-2
- 3 socket contacts 1.8 - 3.3 mm	283025-1

The mating connector is not included in the delivery contents. This can be supplied by Bosch Rexroth on request.

Before finalizing your design, request a binding installation drawing. Dimensions in mm.

# Connector for solenoids

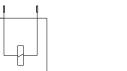
### **DEUTSCH DT04-2P-EP04**

Molded, 2-pin, without bidirectional suppressor diode (standard)	Ρ
Molded, 2-pin, with bidirectional suppressor diode (only for switching solenoid on control module EZ1/2, DA)	a
There is the following type of protection with mounted mating connector:  IP67 DIN/EN 6052	29
and IP69K DIN 40050-	9

The protection circuit with bidirectional suppressor diode is needed to limit overvoltages. Overvoltages are caused by switching off the current with switches, relay contacts or by disconnecting the mating connector while voltage is applied.

#### Circuit symbol

Without bidirectional suppressor diode



with bidirectional suppressor diode

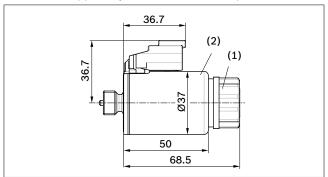


#### Mating connector

DEUTSCH DT06-2S-EP04 Bosch Rexroth Mat. No. R902601804

Consisting of:	DT designation
– 1 housing	DT06-2S-EP04
- 1 wedge	W2S
- 2 sockets	0462-201-16141

The mating connector is not included in the delivery contents. This can be supplied by Bosch Rexroth on request.



#### Changing connector orientation

If necessary, you can change the connector orientation by turning the solenoid housing.

To do this, proceed as follows:

- 1. Loosen the mounting nut (1) of the solenoid. To do this, turn the mounting nut (1) one turn counter-clockwise.
- 2. Turn the solenoid body (2) to the desired orientation.
- 3. Retighten the mounting nut. Tightening torque: 5+1 Nm. (WAF26, 12-sided DIN 3124)

On delivery, the connector orientation may differ from that shown in the brochure or drawing.

# Rotary inch valve

Any reduction of the pilot pressure possible, independently of the drive speed, through mechanical actuation of the position lever. Maximum angle of rotation 90°, lever position: any.

The valve is arranged separately from the pump and is connected to the pump by a hydraulic control line via port  $P_S$  (maximum line length: approx. 2 m).

The rotary inch valve must be ordered separately.

NG	Material No.	Actuating direction of the position lever
28, 40, 56, 71, 90	R902048734 R902048735	right left
125	R902048740 R902048741	right left
180, 250	R902048744 R902048745	right left

#### Note:

The rotary inch valve can be used regardless of the control module.

#### Schematic:

Hydraulic control, speed-related, DA with separately attached rotary inch valve

Rotary inch valve (see material number)

Rotary inch valve (see material number)

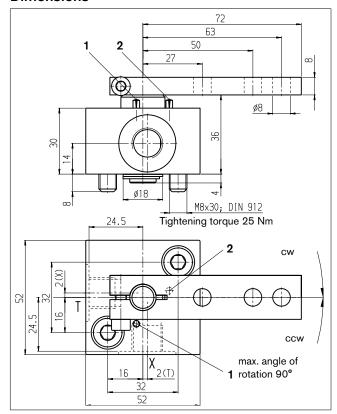
Rotary inch valve (see material number)

Fa Fa1 Fe Fs Ma B

T1 T2 X1 X2 G M<sub>H</sub> S M<sub>A</sub> A

# Before finalizing your design, request a binding installation drawing. Dimensions in mm.

### **Dimensions**



#### Note

Limitation 1 and 2 are function stops for inching. They are not to be used as a mechanical limitation within the system. We recommend limiting the angle of rotation to 85° within the system.

Designation	Port for	Standard	Size <sup>1)</sup>	Maximum pressure [bar] <sup>2)</sup>	State <sup>3)</sup>
Χ	Pilot pressure	DIN 3852	M14 x 1.5; 12 deep	40	0
Т	Drain line	DIN 3852	M14 x 1.5; 12 deep	3	0

- 1) Observe the general instructions on page 68 for the maximum tightening torques.
- 2) Momentary pressure spikes may occur depending on the application. Keep this in mind when selecting measuring devices and fittings.
- O = Must be connected (plugged on delivery)
   X = Plugged (in normal operation)

# Installation dimensions for coupling assembly

Before finalizing your design, request a binding installation drawing. Dimensions in mm.

To ensure that rotating components (coupling hub) and fixed components (housing, circlip) do not come into contact with each other, the installation conditions described here must be observed. This depends on the pump size and the splined shaft.

#### Size 28 and 40 (with free turning):

SAE and DIN splined shaft
 Note diameter of free turning (size 28: Ø72, size 40: Ø80).

### Size 56 to 250 (without free turning):

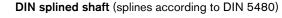
- SAE splined shaft (shaft S or T)

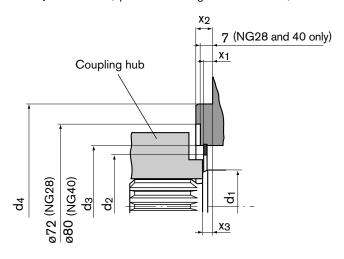
The outer diameter of the shoulder on coupling hub must be smaller than the inner diameter of the circlip  $\mathbf{d}_2$  in the area near the drive shaft collar (dimension  $x_2 - x_3$ ).

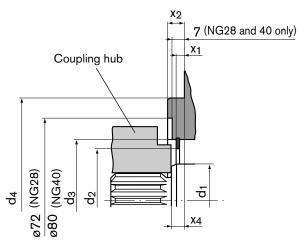
DIN splined shaft (shaft Z or A)

The outer diameter of the shoulder on coupling hub must be smaller than the case diameter  $\mathbf{d}_3$  in the area near the drive shaft collar (dimension  $x_2 - x_4$ ).

### SAE splined shaft (splines according to ANSI B92.1a)







NG	ød <sub>1</sub>	ød <sub>2 min</sub>	ød₃	ød₄	<b>x</b> <sub>1</sub>	<b>x</b> <sub>2</sub>	<b>x</b> <sub>3</sub>	<b>x</b> <sub>4</sub>
28	35	43.4	55 ±0.1	101.6	3.3 +0.2	9.5 _0.5	8 +0.9 -0.6	10 +0.9 -0.6
40	40	51.4	63 ±0.1	127	4.3 +0.2	12.70.5	8 +0.9 -0.6	10 +0.9 -0.6
56	40	54.4	68 ±0.1	127	7.0 <sup>+0.2</sup>	12.70.5	8 +0.9 -0.6	10 +0.9 -0.6
71	45	66.5	81 ±0.1	127	7.0 <sup>+0.2</sup>	12.70.5	8 <sup>+0.9</sup> <sub>-0.6</sub>	10 +0.9 -0.6
90	50	66.5	81 ±0.1	152.4	6.8 +0.2	12.70.5	8 +0.9 -0.6	10 +0.9 -0.6
125	55	76.3	91 ±0.1	152.4	7.0 +0.2	12.70.5	8 +0.9 -0.6	10 +0.9 -0.6
180	60	88	107 ±0.1	165.1	7.4 <sup>+0.2</sup>	15.9 _0.5	8 +0.9 -0.6	10 +0.9 -0.6
250	75	104.6	121	165.1	6.3 +0.2	15.9 _0.5	8 +0.9 -0.6	10 +0.9 -0.6

# Installation instructions

### General

During commissioning and operation, the axial piston unit must be filled with hydraulic fluid and air bled. This must also observed following a relatively long standstill as the axial piston unit may drain back to the reservoir via the hydraulic lines.

Particularly in the installation position "drive shaft upwards" filling and air bleeding must be carried out completely as there is, for example, a danger of dry running.

The case drain fluid in the pump housing must be directed to the reservoir via the highest available drain port  $(T_1, T_2)$ .

For combinations of multiple units, make sure that the respective case pressure in each unit is not exceeded. In the event of pressure differences at the drain ports of the units, the shared drain line must be changed so that the minimum permissible case pressure of all connected units is not exceeded in any situation. If this is not possible, separate drain lines must be laid if necessary.

To achieve favorable noise values, decouple all connecting lines using elastic elements and avoid above-reservoir installation

In all operating conditions, the suction and drain lines must flow into the reservoir below the minimum fluid level. The permissible suction height  $h_S$  results from the overall loss of pressure; it must not, however, be higher than  $h_{S \text{ max}} = 800$  mm. The minimum suction pressure at port S must also not fall below 0.8 bar absolute during operation (cold start 0.5 bar absolute).

### Installation position

See the following examples 1 to 12. Further installation positions are available upon request.

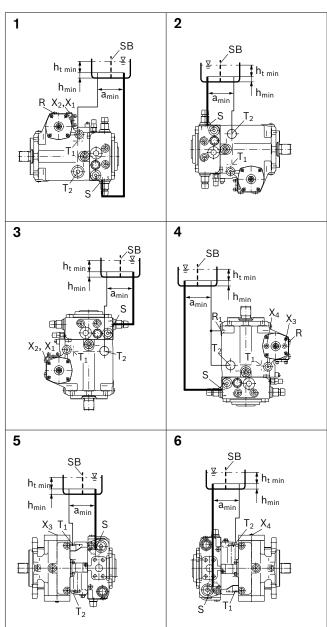
Recommended installation positions: 1 and 2.

#### Notes

- Size 71 to 250
   With the "drive shaft upwards" installation position, an R<sub>1</sub>-port is necessary (special version).
- If it is not possible to fill the stroking chambers via X<sub>1</sub> to X<sub>4</sub> in the final installation position, this must be done prior to installation.
- To prevent unexpected actuation and damage, the stroking chambers must be bled via the ports X<sub>1</sub>, X<sub>2</sub> or X<sub>3</sub>, X<sub>4</sub> depending on the installation position.
- In certain installation positions, an influence on the control characteristics can be expected. Gravity, dead weight and case pressure can cause minor shifts in control characteristics and changes in response time.

#### Below-reservoir installation (standard)

Below-reservoir installation means that the axial piston unit is installed outside of the reservoir below the minimum fluid level.



Installation position	Bleeding the case	Bleeding the stroking chamber	Filling
1	R	$X_1, X_2$	$S + T_1 + X_1 + X_2$
2	_	_	S + T <sub>2</sub>
3	_	X <sub>1</sub> , X <sub>2</sub>	$S + T_2 + X_1 + X_2$
4	R <sub>1</sub>	X <sub>3</sub> , X <sub>4</sub>	$S + T_2 + X_3 + X_4$
5	-	X <sub>3</sub>	$S + T_1 + X_3$
6	_	X <sub>4</sub>	S + T <sub>2</sub> + X <sub>4</sub>

Note instructions!

Key, see page 64.

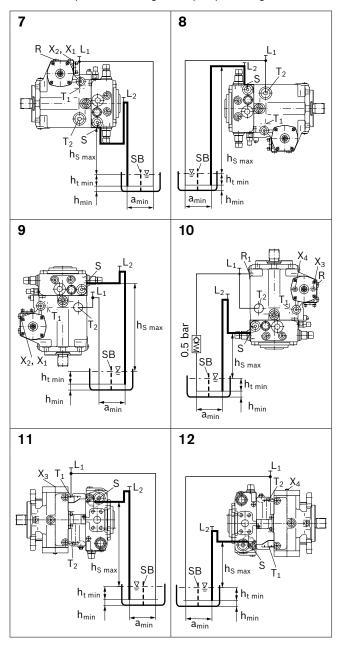
# Installation instructions

#### Above-reservoir installation

Above-reservoir installation means that the axial piston unit is installed above the minimum fluid level of the reservoir.

Observe the maximum permissible suction height  $h_{S max} = 800 \text{ mm}$ .

Recommendation for installation position 10 (drive shaft upward): A check valve in the drain line (cracking pressure 0.5 bar) can prevent draining of the pump housing.



Installation position	Bleeding the case	Bleeding the stroking chamber	Filling
7	L <sub>2</sub> + R	X <sub>1</sub> , X <sub>2</sub>	$L_1 + L_2 + X_1 + X_2$
8	$L_2$ (S) + $L_1$ ( $T_2$ )	_	$L_2$ (S) + $L_1$ (T <sub>2</sub> )
9	$L_2$ (S) + $L_1$ ( $T_2$ )	X <sub>1</sub> , X <sub>2</sub>	$L_2$ (S) + $L_1$ ( $T_2$ ) + $X_1$ + $X_2$
10	$L_2 + R_1$	X <sub>3</sub> , X <sub>4</sub>	$L_1 + L_2 + X_3 + X_4$
11	$L_2$ (S) + $L_1$ (T <sub>1</sub> )	X <sub>3</sub>	$L_2$ (S) + $L_1$ (T <sub>1</sub> ) + $X_3$
12	$L_2$ (S) + $L_1$ ( $T_2$ )	X <sub>4</sub>	L <sub>2</sub> (S) + L <sub>1</sub> (T <sub>2</sub> ) + X <sub>4</sub>

Comply with notes on page 65!

L<sub>1</sub>, L<sub>2</sub> Filling / air bleed
 R Air bleed port
 S Suction port
 T<sub>1</sub>, T<sub>2</sub> Drain port

SB Baffle (baffle plate)

 $\mathbf{h}_{\mathrm{t}\,\mathrm{min}}$  Minimum required immersion depth (200 mm)

 $\mathbf{h}_{\min}$  Minimum required spacing to reservoir bot-

tom (100 mm)

h<sub>S max</sub> Maximum permissible suction height (800 mm)

a<sub>min</sub> When designing the reservoir, ensure adequate space between the suction line and the drain line.
 This prevents the heated, return flow from being drawn directly back into the suction line.

# Notes

# General instructions

- The pump A4VG is designed to be used in closed circuit.
- The project planning, installation and commissioning of the axial piston unit requires the involvement of qualified personnel.
- Before using the axial piston unit, please read the corresponding instruction manual completely and thoroughly. If necessary, these can be requested from Bosch Rexroth.
- During and shortly after operation, there is a risk of burns on the axial piston unit and especially on the solenoids. Take appropriate safety measures (e. g. by wearing protective clothing).
- Depending on the operating conditions of the axial piston unit (operating pressure, fluid temperature), the characteristic may shift.
- Service line ports:
  - The ports and fastening threads are designed for the specified maximum pressure. The machine or system manufacturer must ensure that the connecting elements and lines correspond to the specified application conditions (pressure, flow, hydraulic fluid, temperature) with the necessary safety factors.
  - The service line ports and function ports can only be used to accommodate hydraulic lines.

- The data and notes contained herein must be adhered to.
- The product is not approved as a component for the safety concept of a general machine according to ISO 13849.
- The following tightening torques apply:
  - Fittings:
     Observe the manufacturer's instructions regarding the tightening torques of the fittings used.
  - Mounting bolts:
     For mounting bolts with metric ISO thread according to DIN 13 or thread according to ASME B1.1, we recommend checking the tightening torque in individual cases in accordance with VDI 2230.
  - Female threads in the axial piston unit:
     The maximum permissible tightening torques M<sub>G max</sub> are maximum values of the female threads and must not be exceeded. For values, see the following table.
  - Threaded plugs:
     For the metallic threaded plugs supplied with the axial piston unit, the required tightening torques of threaded plugs M<sub>V</sub> apply. For values, see the following table.

Ports Standard	Size of thread	Maximum permissible tightening torque of the female threads M <sub>G max</sub>	Required tightening torque of the threaded plugs M <sub>V</sub> <sup>1)</sup>	WAF hexagon socket of the threaded plugs
DIN 3852	M10 x 1	30 Nm	15 Nm <sup>2)</sup>	5 mm
	M12 x 1.5	50 Nm	25 Nm <sup>2)</sup>	6 mm
	M14 x 1.5	80 Nm	35 Nm	6 mm
	M16 x 1.5	100 Nm	50 Nm	8 mm
	M18 x 1.5	140 Nm	60 Nm	8 mm
	M22 x 1.5	210 Nm	80 Nm	10 mm
	M26 x 1.5	230 Nm	120 Nm	12 mm
	M33 x 2	540 Nm	225 Nm	17 mm
	M42 x 2	720 Nm	360 Nm	22 mm
	M48 x 2	900 Nm	400 Nm	24 mm

<sup>1)</sup> The tightening torques apply for screws in the "dry" state as received on delivery and in the "lightly oiled" state for installation.

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The data specified above only serve to describe the product. No statements concerning a certain condition or suitability for a certain application can be derived from our information. The information given does not release the user from the obligation of own judgment and verification. It must be remembered that our products are subject to a natural process of wear and aging.

Subject to change.

<sup>2)</sup> In the "lightly oiled" state, the  $M_V$  is reduced to 10 Nm for M10 x 1 and 17 Nm for M12 x 1.5.